

On Semi-Uniformity, Quasi-Uniformity, Local Uniformity and Uniformity

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Abstract:- In this paper we shall study the notions of semi-uniformity, quasi-uniformity, local uniformity and uniformity and we can establish some relations among them. Here it can be shown that a uniform space has always a base of symmetric vicinities.

Keywords:- Uniformity, Vicinity, Symmetric, Diagonal Filter.

I. INTRODUCTION

If the symmetry, condition in the definition of a pseudometric is deleted, the notion of a quasi-pseudometric is obtained. Asymmetric distance functions already occurs in the work of hausdorff in the beginning of the twentieth century when in his book on set-theory he discusses what is know called the hausdroff metric of a metric space.

A family of pseudo-metrices on a set generates uniformity. Similarly, a family of quasi-pseudometrices on a set generates a quasi- uniformity.

In 1937 Weil- published his booklet on uniformites, which is now usually considered as the beginning of the modern-theory of uniformities. Three years later Tukey suggested an approach to uniformities via uniform coverings. The study of quasi-uniformities started in 1948 with Nachbin's investigations on uniform pre-ordered preorder is given by the intersection of the entourages of a (filter) quasi-uniformity u and sup-uniformity uvu^{-1} .

II. NOTIONS OF SEMI-UNIFORMITY, QUASI-UNIFORMITY, LOCAL UNIFORMITY AND UNIFORMITY

➤ *Definition :*

Let X be a non-empty set and let $\Delta = \{(x, x) \mid x \in X\}$ be the 'diagonal'. A subset $A \subset X \times X$ is said to be 'symmetric' if $A = A^{-1}$, where $A^{-1} = \{(x, y) \in X \times X : (y, x) \in A\}$. For $A, B \subset X \times X$ we define $A, B = \{(x, y) : (x, z) \in A \text{ and } (z, y) \in B \text{ for some } z \in X\}$

The set A . A is also written as A^2

If $A, B, C \subset X \times X$ then it is easy to see that

- (i) $A \cdot \Delta = \Delta \cdot A = A$;
- (ii) $A \cdot (B, C) = (A \cdot B) \cdot C$;
- (iii) $(A \cdot B)^{-1} = B^{-1} \cdot A^{-1}$
- (iv) $A^{n+1} = A^n \cdot A$ and $A^n \cdot A^m = A^{n+m}$;
- (v) $(A^n)^{-1} = (A^{-1})^n$
- (vi) $A \subset B \Rightarrow A^{-1} \subset B^{-1}$ and $A^n \subset B^n$
- (vii) If A is symmetric so is A^n for each positive interger n .

Proposition :

Let B be a filter base on $X \times X$ such that for each $U \in B$ we have

- (i) $\Delta \subseteq U$ (ii) $V^{-1} \subset U$ for some $V \in B$ and (iii) $V^2 \subset U$ for some $V \in B$. Then the filter $F(B)$ determined by B satisfies
- (i)' $\Delta \subseteq U$ for all $U \in F(B)$
- (ii)' $U^1 \in F(B)$ for all $U \in F(B)$;
- (iii)' For all $U \in F(B)$, there is a $V \in F(B)$ such that $V^2 \subset U$.

Conversely, suppose F is a filter on $X \times X$ satisfying (i)' to (iii)'.

Then the conditions (i) to (iii) are satisfied by every filterbase B which determines F .

Proof:

(i)' is obvious for if $U \in F(B)$, then $U \supseteq U_1$ for some $U_1 \in B$ and by (i) we have $\Delta \subseteq U_1 \subset U$. To prove (ii)' and (iii)', consider any $U \in F(B)$. Then $W \subset U$ for some $W \in B$. Using (ii) we have a $V \in B \subset F(B)$ satisfying

$V^1 \subset W \subset U$ and so $V \subset U^1$; that is $U^1 \in F(B)$. Also by (iii) there is a $V \in B$ such that $V^2 \subset W \subset U$ i.e. $V^2 \subset U$.

Conversely, suppose that F is filter on $X \times X$ which satisfies conditions (i)' to (iii)' and let B be a filter base on $X \times X$ which determine F . since $B \subset F(B)$, condition (i) is satisfied. If $U \in B$ then $U^{-1} \in F(B)$ and $V \subset U^{-1}$ for some $V \in B$. Thus $V^{-1} \subset U$ and condition (ii)' is satisfied. Finally, let $U \in B \subseteq F(B)$ and let $W^2 \subset U$. Since $W \in F(B)$, one has $V \subset W$ for some $V \in B$. In particular, we have $V^2 \subset W^2 \subset U$. Hence condition (iii)' is satisfied. This completes that proof.

➤ **Definition :**

Let X be a non-empty set.

A filter \mathcal{U} of subsets of $X \times X$ is said to be a

- (a) semi-uniformity for X if $\Delta \subseteq U$ and $U^{-1} \in \mathcal{U}$ for all $U \in \mathcal{U}$,
- (b) quasi-uniformity for X if $\Delta \subseteq U$ and there exists a $V \in \mathcal{U}$ such that $V^2 \subset U$ for all $U \in \mathcal{U}$,
- (c) Uniformity for X if \mathcal{U} is both a semiuniformity and a quasi-uniformity.
- (d) Local uniformity for X if it is semi-uniformity and for each $U \in \mathcal{U}$ and $x \in X$, there exists a $V \in \mathcal{U}$ such that $V^2[x] \subset U[x]$, \mathcal{U} is said to be Hausdorff (or separated) if $\bigcap \{U : U \in \mathcal{U}\} = \Delta$. The members $U \in \mathcal{U}$ are called the Vicinities. Moreover, $x, y \in X$ are called U -close (or close of order U) if $(x, y) \in U$ (where $U \in \mathcal{U}$).

➤ **Definition :**

Uniform space: A uniform space is a pair (X, \mathcal{U}) where X is a non-empty set and \mathcal{U} is a uniformity for X , i.e. \mathcal{U} is a filter on $X \times X$ satisfying the following conditions:

- [V₁] Every $U \in \mathcal{U}$ contains the diagonal Δ ;
- [V₂] If $U \in \mathcal{U}$ then $U^{-1} \in \mathcal{U}$
- [V₃] for each $U \in \mathcal{U}$ there exists a $V \in \mathcal{U}$ with

$$V^2 \subset U$$

III. COMPARISON OF UNIFORMITIES :

➤ **Definition :**

If \mathcal{U}_1 and \mathcal{U}_2 are both uniformities for a non-empty set X , we say that \mathcal{U}_1 is weaker or coarser than \mathcal{U}_2 (and \mathcal{U}_2 is finer or stronger than \mathcal{U}_1) if $\mathcal{U}_1 \subseteq \mathcal{U}_2$. that is, if every vicinity for \mathcal{U}_1 is also a vicinity for \mathcal{U}_2 .

➤ **Definition :**

A base for a uniformity \mathcal{U} on X is a filterbase β such that $U \in \mathcal{U}$ iff U contains some $B \in \beta$.

Proof (6.2) :

A uniform space (X, \mathcal{U}) has always a base of symmetric vicinities.

Proof :

Let β = the family of all symmetric vicinities i.e. those with $U = U^{-1}$
 For $U \in \mathcal{U}$. Then β is a base for \mathcal{U} since the symmetric vicinity $U \cap U^{-1}$ is contained in the vicinity U for each $U \in \mathcal{U}$.

➤ **Definition :**

Let β_1 and β_2 be two bases for a uniformity \mathcal{U} on a non-empty set X we say that β_1 and β_2 are equivalent if for each $B_1 \in \beta_1$ there exists a $B_2 \in \beta_2$ such that $B_2 \subseteq B_1$ and for each $B_2' \in \beta_2$ there exists $B_1' \in \beta_1$ such that $B_1' \subseteq B_2'$.

Example (1) :

Given a non-empty set X , the indiscrete uniformity $\mathcal{U}_1 = X \times X$ is the weakest uniformity for X and the discrete uniformity $\mathcal{U}_D = \{U \subset X \times X ; \Delta \subseteq U\}$ is the strongest uniformity for X . We note that $\{\Delta\}$ is a base for discrete uniformity for X where as $\{X \times X\}$ is a base for indiscrete uniformity for X .

IV. CONCLUSION

Hence, A uniform space (X, \mathcal{U}) has always a base of symmetric vicinities.

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