

Future-Proofing Road Safety: Adapting ISO 26262 for Advanced V2X Integration

Jherrod Thomas

Certified Functional Safety Expert, Tomco Service Group LLC

The Lion of Functional Safety™

Abstract:- This study investigates the integration of ISO 26262 with Vehicle-to-Everything (V2X) communication technologies. Emphasize the necessity of expanding this safety standard to include vehicle-to-infrastructure integration and addressing additional safety measures to accommodate current vehicles' complex and rapidly evolving networks. The study uses an extensive review approach, which considers existing safety pro-ocols and a qualitative literature synthesis to evaluate current standards and anticipate future requirements from them. It also looks at developments in V2X communication technology while identifying gaps within the present scope of ISO 26262 concerning autonomous and connected cars. The findings indicate a significant improvement in road safety plus efficiency in traffic management by integrating ISO 26262 with V2X communication. Further, the research points out areas such as security lapses, real-time data processing deficiencies, interoperability hitches, and scalability limits. These findings call for amendments to current safety standards so that they can take care of those problems. Failure to include V2X into ISO 26262 may com-promise reliability altogether, hence posing a grave danger to future intelligent transportation systems (ITS)'s dependability. The research concludes that integrating them will help lower risks brought about by the dynamic nature of vehicles' environment, thereby facilitating the establishment of globally solid and safe systems for communicating between vehicles.

Keywords:- ISO 26262, V2X Communication, Vehicle-to-Infrastructure, Functional Safety, Intelligent Transport Systems, Autonomous Vehicles. Vehicle Safety Technology Connected Roads.

I. INTRODUCTION

EHICLE-to-Everything (V2X) communication is a Vbreak through technology that enables automobiles to interact with each other and the surrounding infrastructure. Integrating ISO 26262 with V2X communication, a functional safety standard for automotive systems, aims to improve the dependability and safety of such complex vehicular networks. This section gives an overview of what V2X communication means and its components within the context of next-generation transportation systems.

A. Definition and Components of V2X Communication

➤ Definition:

V2X communication represents a set of technologies through which vehicles can share information with different entities in the transport system, including other vehicles, pedestrians, infrastructure, and networks [1]. This can

Manuscript received August 01, 2024; revised August 21, 2024. happen via cellular networks (C-V2X), dedicated short-range communications (DSRC), or upcoming 5G technologies.

➤ Components:

- Vehicle-to-Vehicle (V2V): This refers to direct data exchange between vehicles to enhance safety by sharing things like speed, location, and heading that help prevent collisions while improving traffic flow [2].
- Vehicle-to-Infrastructure (V2I): This involves exchanging data between cars and road infrastructure, such as traffic lights, signs, or control systems; this integration enables effective traffic management by providing real-time traffic information together with warnings for better road safety [3].
- Vehicle-to-Network (V2N): Vehicles are connected to cellular networks under V2N communication so that they can access internet services for navigation purposes, infotainment among other emergency services, may also be supported; it is through this connectivity that advanced telematics as well cloud-based applications become possible [4].
- Vehicle-to-Pedestrian(V2P): It enhances pedestrian safety by allowing cars to detect them and communicate; drivers can be alerted about potential hazards while pedestrians are also notified, thereby minimizing accidents involving these two parties [5].
- Vehicle-to-Cloud(V2C): Under V2C, data is transmitted between vehicles and cloud servers, which supports big data analytics, real-time traffic updates, and remote diagnostics necessary for innovative city development and autonomous driving technologies [6].

➤ *Integration with ISO 26262:*

ISO 26262 is an inter-national standard for the functional safety of electrical and electronic systems in road vehicles, ensuring that they operate reliably and safely. Integrating V2X communication with ISO 26262 involves extending safety protocols to cater to the dynamic nature of V2X environments. This step enhances the dependability of such systems where all conditions must be met for proper functioning so that no accidents occur while driving on any road [7].

V2X communication is a significant milestone in vehicle technology that benefits road safety, traffic efficiency, and environmental sustainability. By incorporating these systems into ISO 26262 standards, the automotive industry would ensure higher reliability and safety levels, thus opening up possibilities for intelligent transport systems in the future.

B. ISO 26262 Current Scope

ISO 26262 is a standard for functional safety regarding electrical and electronic systems in passenger cars. The standard was first released in 2011 and is based on the broader IEC 61508 standard, modified for use in automotive systems. It gives guidance on how to ensure that automobile components work safely under every condition they might encounter. Some of the highlights of the current scope are:

➤ *System Development Phases:*

- **Concept Phase:** Identify hazards associated with vehicle functions and assess their risks; safety goals and functional safety requirements must be defined at this stage based on an initial architectural description [8].
- **Product Development:** This phase covers system-level development, hardware and software design, detailed implementation, integration testing, specification of safety mechanisms, and verification against safety requirements [7].

➤ *Automotive Safety Integrity Levels (ASILs):*

Risks are classified into four ASILs (A to D) by ISO 26262, where ASIL D represents the highest risk level; classification is done based on severity, exposure, and controllability of hazardous events; each ASIL requires specific rigor for necessary safety measures [9].

➤ *Safety Life-Cycle:*

The whole life cycle from concept through decommissioning should follow a safety approach according to the standard; continuous assessment and validation activities must be conducted to not break compliance throughout the vehicle's lifetime [10].

➤ *Software and Hardware Development:*

- **Software:** ISO/IEC/IEEE – Joint Standard for Systems Engineering and Software Requirements Specification mandates specific processes such as requirements specification, architectural design, and unit implementation/testing while model-based development together with formal verification methods should be employed where applicable [11].
- **Hardware:** Metrics for random hardware failures should be defined during this phase; the standard provides guidelines for handling these failures by implementing safety mechanisms [9].

➤ *Safety Management and Processes:*

Establish a safety culture within the organization; establish roles and responsibilities for safety management throughout the life cycle; ensure proper safety assurance, including creating safety cases that collect evidence showing that all necessary requirements have been met [12].

➤ *Tool Qualification:*

The standard requires that software tools used in the development process be qualified so as not to function incorrectly or introduce any risk to achieving the desired level of functional safety according to defined requirements; it gives guidelines on tool classification/validation/qualification, etc. [13].

➤ *Extending Scope:*

The Second Edition of ISO 26262 expands the applicability domain beyond just passenger cars into other categories like motorcycles, trucks, buses, etc., thus making it more comprehensive in terms of its coverage and depth of safety provisions [14].

ISO 26262 is a wide-ranging standard that tackles functional safety in automotive systems by clearly defining a safety lifecycle, strict development processes, and demanding safeguards. It covers everything from product concept to disposal stages, ensuring all aspects of vehicle electronics and software are treated with utmost care for reliability and safe operation in modern vehicles.

C. The Gap in Existing Standards Concerning V2X Integration

Even though V2X (Vehicle-to-Everything) interaction technology has been advancing, there are still some notable gaps in the current standards, which prevent them from being widely adopted or integrated well. This part of the article will highlight these gaps and challenges within current standards for V2X integration.

- **Security and Privacy Concerns:** Some significant security gaps have been found within specific V2X protocols like IEEE 802.11p or cellular-based solutions (C-V2X). These systems do not always provide enough protection against cyber attacks, unauthorized access to data, or privacy breaches – all essential elements in communication between vehicles being trusted and safe [15].
 - **Interoperability and Coexistence:** A big challenge remains around how different versions of DSRC can coexist with C-V2X and interoperability between them, mainly because there aren't any globally recognized frameworks or standards for developing such things. However, if we combine both IEEE 802.11p standards with a cellular-based solution, then it might work, though not easy to implement practically [16].
 - **Latency and Real-time Constraints:** The ultra-low latency requirement needed by many autonomous driving safety-related applications, among others under the V2X umbrella, cannot be met using currently available communication performance [17].
 - **Scalability and Network Congestion:** Vehicle density is one of the most significant issues facing existing V2X network systems, which will see an increase over time due to its popularity; however, there is still a need for better resource conflict management strategies so that they can achieve high capacity performance without compromising safety [18].
 - **Integration with Existing Infrastructure:** The current infrastructure in place for V2X communication systems might not be able to accommodate electric/electronic (E/E) architectures used by vehicles around them or even the road itself; this, therefore, calls for more guidelines and standards on how best they can be integrated [19].
 - **Standardization and Regulatory Frameworks:** A global approach towards standardizing V2X technologies is crucial if they are to work effectively because right now, different parts of the world have their own set regionally recognized. Still, inconsistent standards make it difficult for these systems to communicate with each other – there should be one common understanding worldwide about what constitutes good practice here [20].
- Addressing current gaps within V2x standards will enable successful integration and deployment of V2X communication systems. To overcome these deficiencies, security enhancements must be made, interoperability improved, latency reduced, and scalability addressed through efficient resource management [18].
- D. Goals of the Study*
- The objective of the review paper is to address various goals that could advance the field of V2X communication about automotive safety standards. The following are the main targets of the study:
- **Identify and Analyze Gaps in Current Standards:** The study should look at all existing gaps within today's state-of-the-art V2X communications standardization efforts, considering security, interoperability, latency, scalability problems, and integration with existing vehicle infrastructure [15].
 - **Extend ISO 26262 to Include V2X Integration:** This review proposes extensions on top of functional safety requirements for electric/electronic systems in vehicles described by ISO 26262 so that they can adequately cover the more dynamic and complex nature of communication brought about by Vehicular Communication Systems, particularly those involving Infrastructure [9].
 - **Evaluate Security and Privacy Measures:** Another critical goal is evaluating current security measures adopted in different V2X standards, intending to point out their weaknesses, which, if not addressed, may compromise safe operation between vehicles or between them and other road users like pedestrians; this should also involve privacy protection mechanisms [21].
 - **Develop a Framework for Standardized Protocols:** Creating a framework that will define standard rules necessary for ensuring seamless data exchange among diverse technological options employed within DSRC & C-V2X environment, thus improving the efficiency and reliability of vehicle-to-everything (V2X) communication systems [20].
 - **Assess Real-time and Latency Requirements:** Evaluating temporal constraints necessary for the practical realization of various applications based on V2X is crucial, especially when it comes to safety-critical situations such as collision avoidance systems in autonomous cars [17].
 - **Propose Solutions for Scalability and Network Congestion:** Suggesting ways through which scalability challenges can be overcome without compromising performance under high-density vehicular environments while at the same time ensuring that network resources are not wasted due to congestion caused by too many messages trying to access limited bandwidth [18].
 - **Enhance Integration with Vehicular and Road Infrastructure:** This study aims to provide practical guidance regarding how these two kinds of systems can work together seamlessly. Hence, it will address both technical issues associated with their convergence and operational concerns related to physical realization, i.e., where various elements should be placed along road networks so that they may easily interconnect among themselves, thus forming efficient communication links [19].
 - **Provide a Road-map for Future Research:** Last but not least, one goal of this research is to provide systematic guidance on what areas require further investigation or development efforts to achieve a fully integrated, safe, and efficient intelligent transportation system through vehicular communication technologies like V2X, thereby acting as a blueprint for future endeavors in similar fields [4].

II. OVERVIEW OF V2X COMMUNICATION TECHNOLOGIES

Intelligent transportation systems (ITS) aim to improve road safety, traffic efficiency, and the overall driving experience. Vehicle-to-everything (V2X) communication technology is a major part of these systems. This includes vehicle-to-vehicle (V2V), vehicle-to-infrastructure (V2I), and vehicle-to-pedestrian (V2P) communications, among others, which are all different facets of the V2X ecosystem.

A. Vehicle-to-Vehicle (V2V)

➤ *Description and Functionality:*

Vehicle-to-vehicle communication refers to the direct exchange of data between cars to achieve cooperative driving and enhance safety standards. Usually, this type of communication takes place over short-medium ranges using either dedicated short-range communications (DSRC) or cellular V2X technologies where DSRC can be used for long-range as well as short-range, whereas C-V2X can only cover shorter distances but with higher bandwidths. The main idea behind V2V is that vehicles share information about their speed, position, and direction, thereby allowing them to anticipate potential dangers in real time and react proactively [3].

➤ *Use Cases and Benefits:*

- **Collision Avoidance:** One of the most significant applications of V2V communication is in collision avoidance. Advanced driver assistance systems leverage V2V communications to detect potential collisions, issue alerts, or even take automated actions like braking. For instance, when a car ahead suddenly applies brakes, it can signal through V2V, alerting the following vehicles to the need for immediate action. This proactive safety measure reassures drivers and significantly reduces the risk of accidents [4].
- **Traffic Flow Optimization:** V2V communication also plays a crucial role in traffic flow optimization. Vehicular ad hoc networks, based on VANET, can be used to share real-time traffic information between vehicles. This sharing leads to flow optimization, reducing congestion levels and enhancing travel times. Vehicles can adjust their speeds to maintain steady flows, minimizing stop-and-go scenarios. This application of V2V communication offers hope for a future with reduced traffic congestion [22].

- **Emergency Vehicle Coordination:** V2V communications enable emergency vehicles to transmit their intended path through other cars in traffic, ensuring quick and safe passage during emergencies. This coordination dramatically reduces response times for such situations [23].
- **Platooning:** Vehicle platoons are easily facilitated through V2V communication. Several autos travel closely behind each other at high speeds on highways, reducing air resistance and thus saving fuel consumption. Dhawankar et al.(2021) [17] further state that automated driving systems using data from V2V can maintain optimal spacing between them.

Vehicle-to-vehicle (V2V) communication is a critical part of vehicle-to-everything (V2X) technology, which realizes various advantages like safety improvement, traffic flow optimization, and fuel economy enhancement. To achieve this, cars will have to exchange information with each other in real-time, thereby making V2V communication an integral component for the future development of smart city transport systems.

B. Vehicle-to-Infrastructure (V2I)

➤ *Explanation and Usefulness:*

Vehicle-to-infrastructure (V2I) communication exchanges information between vehicles and traffic infrastructure, like signals, signs, or systems for managing traffic. The intention behind this kind of talk is to prevent road accidents and improve traffic flow efficiency and the overall driving experience by enabling real-time data sharing among cars and with the environment in which they operate on the roads. Different technologies are used in V2I communications, such as DSRC (Dedicated Short Range Communications), C-V2X (Cellular Vehicle To Everything), 5G networks, and others through which these data can be transmitted over short distances up to medium-range areas [3].

Figure 1 depicts an urban intersection where V2X communication is put into effect. The diagram shows how cars, infrastructure and people work together to increase the efficiency of traffic flow while ensuring safety. This allows traffic signals, vehicle movements and pedestrian crossings to be synchronized thus minimizing accidents and enhancing general traffic performance [2].

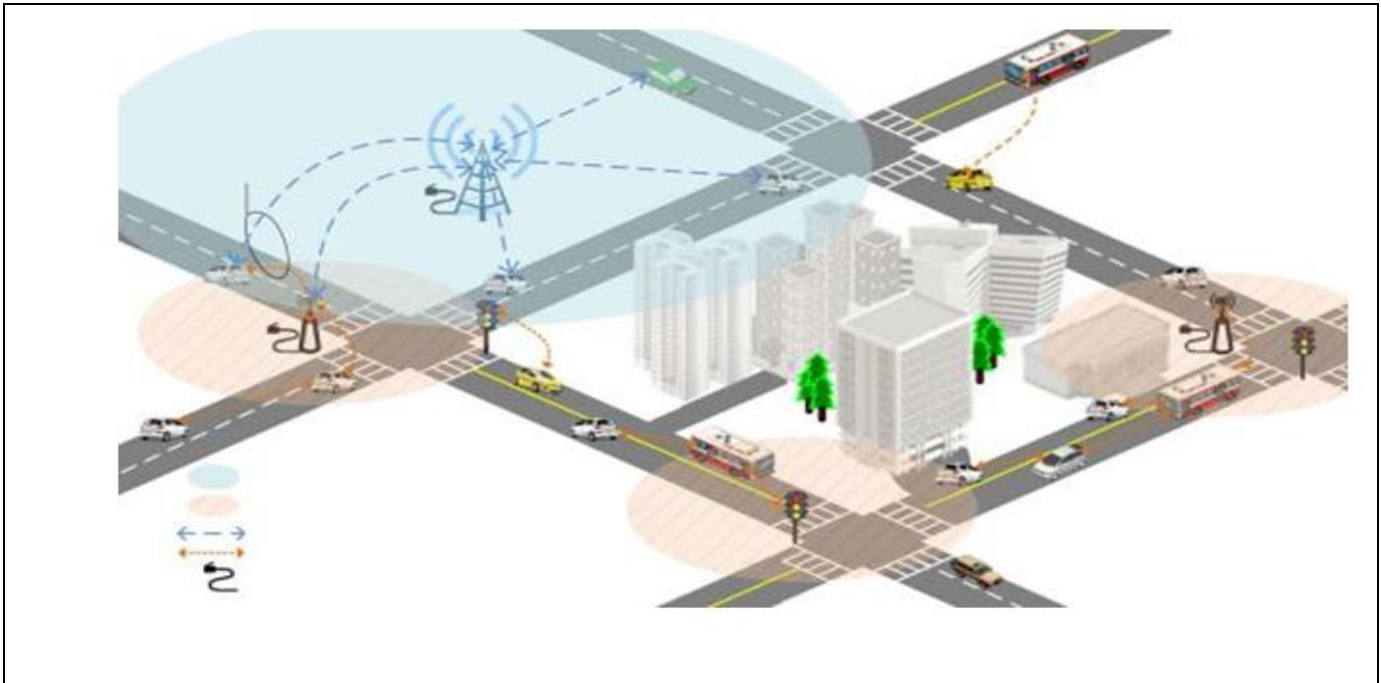


Fig 1: V2X Communications Within a Hybrid Urban Environ-Ment, Combining DSRC and Cellular Technologies to Enhance Connectivity and Coordination among Vehicles, Infrastructure, and Pedestrians

➤ *Use Cases with their Benefits:*

- **Traffic Signal Optimization:** V2I communication makes real-time adaptation of traffic signals based on current traffic conditions possible. For instance, lights may change timings so that there will be less congestion; also, by interacting with approaching vehicles, it becomes easier to anticipate and manage different types of flows at intersections more effectively, thereby improving overall network performance [2].
- **Safety Warnings & Hazard Alerts:** Infrastructure should communicate warnings about dangerous spots due to construction works or bad weather conditions, thus heightening driver consciousness about safety while driving through those areas. This allows drivers to either slow down their speed or take another route depending on what they think might save them from harm, significantly reducing accident rates [4].
- **Enhanced Emergency Response:** V2I's real-time control over traffic lights helps emergency vehicles move faster and safer across junctions, reducing incidents involving ambulances responding to calls within cities or towns [6].
- **Parking Management:** It decreases the time spent looking at a parking lot by providing instant parking availability information in real-time. It also helps reduce car emissions that stand still [24].
- **Toll Collection and Traffic Management:** Thanks to V2I, vehicles can pay tolls automatically without contacting people or things. This allows them to communicate with toll booths, among other benefits, like streamlining toll

collections or improving traffic flow management systems' efficiency [25].

Vehicle-to-infrastructure communication is one part of the V2X system that can optimize traffic, improve safety, and quicken emergency response times, among other advantages. Modern transport becomes efficient when cars exchange live data with their environment through this technology. The use of V2X communication in Cooperative Adaptive Cruise Control (CACC) and platooning scenarios is shown in Figure 2. It demonstrates how accurate vehicle-to-vehicle communication can lead to reduced following distances, as well as coordinated lane merging at high speeds. Apart from improving traffic flow efficiency, this combination also greatly enhances safety on roads by lowering the chances of abrupt braking or changing lanes [2].

C. Vehicle-to-Person (V2P)

➤ *Explanation and Features:*

Vehicle-to-Everything (V2X) technology is a system that allows cars to communicate directly with pedestrians. It aims to improve pedestrian safety, where vehicles can identify and communicate with people using compatible devices such as smartphones or dedicated V2P transmitters. Various communication protocols are used in this technology, including Dedicated Short-Range Communications (DSRC), Cellular V2X (C-V2X), and emerging 5G networks for data transmission over short to medium ranges [4].

➤ *Use Cases and Benefits:*

Avoiding Collisions: The main application of vehicle-to-pedestrian communication is preventing accidents between cars and people on foot. Alerts can be sent to vehicles about

nearby pedestrians' locations and move-ments, which enables them to take preventive measures like slowing down or stopping altogether. Such capability becomes handy when visibility is poor or in areas congested by human traffic [2].

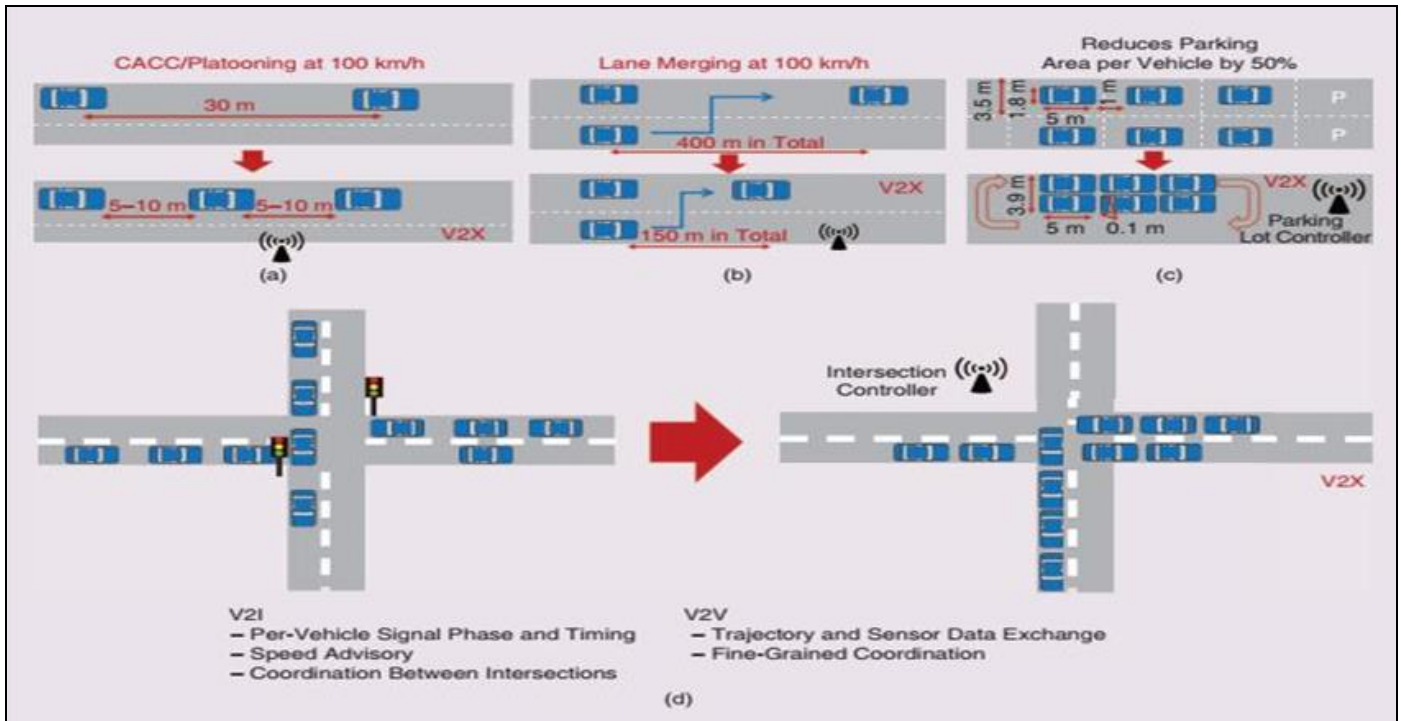


Fig 2: Advanced V2X Use Cases Demonstrate the Significant Improvements Anticipated by 5G V2X Technology.

These En-Hancements Include Quicker and More Precise Maneuver Execution, Optimized Space Utilization for Parking, and Increased Traffic Throughput At Intersections. Illustrated Examples Encom-Pass (A) Cooperative Adaptive Cruise Control (CACC) And Platooning [26], (B) Lane Or Road Merging [26], (C) Automated Parking in Connected Environments [27], and (D) Cooperative Control at Intersections [26]

- Safety around Crosswalks: Infrastructure detecting pedestrians waiting to cross the road can communicate with vehicles through V2P systems for better safety at crosswalks. The system should then warn approaching cars so that accidents do not happen at these points where people walk across busy highways on foot. Traffic signals may also incorporate this technology to ensure efficient pedestrian flow management [25].
- Accessibility Enhancement: Through V2P communication designed to create awareness for persons with disabilities, drivers and walkers could receive auditory or tactile notifications. For instance, visually impaired individuals may receive warnings concerning approaching automobiles, while motorists can be informed about those crossing streets who might need more time due to their physical condition [23].
- Emergency Situations: In an emergency, it becomes necessary to communicate with pedestrians about approaching emergency vehicles using V2P. This enables them to clear off quickly, making it possible for the responders to access crowded or intricate environments [6].
- School Zones: V2P technology in school zones can alert drivers to the presence of children. Alerts about kids crossing roads or playing near them can be sent to cars, prompting motorists to exercise more caution and lower speed levels [24].
- Vehicle-to-Pedestrian (V2P) communication is essential for pedestrian safety because vehicles can share real-time information with people on foot. This development has several advantages, such as preventing collisions, making crosswalks safer, enabling accessibility for those with disabilities, among other benefits, and ensuring efficiency in responding to emergencies. Furthermore, being part of a broader V2X ecosystem significantly contributes to creating safe cities with better traffic management systems.

D. Vehicular-to-Network (V2N)

➤ *Definition and Purpose:*

Communication between vehicles and the network is referred to as Vehicle-to-Network (V2N), and it forms part of the more extensive vehicle-to-everything communication

system. Examples of network infrastructures interacting with cars include cloud services and cellular networks. With this type of communication, automobiles can access internet connections, share real-time data with remote servers, and use other cloud-based vehicle services. In addition to using current technology like LTE (Long-Term Evolution), 5G and future 6G networks are also utilized by V2N so that communication may be fast and reliable enough [4].

➤ *Applications and Advantages:*

- **Traffic Control and Optimization:** Vehicles can talk to traffic control centers through V2N, which will use aggregated information from all cars involved to optimize traffic flow, manage congestion, reduce travel time, etc. For instance, analyzing live traffic data could adjust junction timings dynamically, thereby improving overall efficiency [25].
- **Safety and Emergency Services:** Safety messages concerning road dangers, accidents, or unfavorable weather conditions can be sent out using V2N. These messages are shared with nearby vehicles and emergency response teams, thus enhancing situational awareness while allowing for quicker reactions during emergencies [6].
- **Infotainment and Telematics:** Cloud-based infotainment services, which comprise streaming music/videos plus real-time navigation updates, among other things, are made possible by V2N. In addition, over-the-air diagnostics, software upgrades, vehicle condition monitoring, etc., through telematics can also be done over the network, thus increasing convenience levels in modern cars [3].
- **Autonomous Driving Support:** V2N can support the continuous provision of required navigational information for decision-making during autonomous vehicle navigation. It also helps coordinate different autonomous cars and infrastructures that may have relevant data, such as buildings or road signs. Therefore, self-driving systems' fast and safe operation requires high bandwidth and low latency network connections [24].
- **Fleet Management:** Fleet owners can remotely monitor their fleets using V2N. This includes tracking locations, monitoring drivers' behavior, optimizing routes, and scheduling maintenance. Thanks to real-time updates brought about by communication via V2N, operational costs can be reduced while at the same time improving efficiency levels [23].

Vehicle-to-network (V2N) is an essential part of the vehicle-to-everything ecosystem because it improves traffic management, ensures safety, provides advanced infotainment services, and supports autonomous driving. In fact, modern transportation cannot function without the real-time exchange of data between vehicles and network infrastructure, which greatly expands the functionality, effectiveness, and safety of transport systems.

E. New V2X Communication Technologies

➤ *Cutting-edge and Future V2X Technologies:*

- **The auto-motive and transport industries** are about to change because of the emerging vehicle-to-everything (V2X) communication technologies that offer advanced solutions for connected and autonomous vehicles. These technologies endeavor to improve safety, efficiency, and convenience in transportation systems.
- **5G and Beyond: Deploying 5G networks** is crucial to developing V2X technologies. In real-time communication between vehicles and infrastructure, 5G offers low latency, high bandwidths, and reliable connectivity, which are essential features. By providing faster data transmission speeds and improved reliability, future advancements such as 6G will enhance these capabilities even further [28].
- **Integrated Sensing and Communications (ISAC):** ISAC technology integrates communication ability with sensing capability into one system. This integration allows a car or any other type of vehicle to communicate with others while at the same time sensing its environment, thereby increasing situational awareness, which leads to more advanced driving assistance systems being enabled. High-precision localization is made possible through ISAC, which also promotes collision avoidance and efficient traffic management [28].
- **Cellular V2X (C-V2X):** C-V2X technology is based on LTE/5G that leverages existing cellular networks to provide robust V2X communication capabilities. Various use cases are supported by C-V2X, including vehicle-to-vehicle (V2V), vehicle-to-infrastructure (V2I), and vehicle-to-network (V2N) communications. Compared to traditional DSRC (Dedicated Short Range Communications), it has better range coverage, reliability, and scalability [4].

➤ *Integration with Smart Cities and IoT:*

Integrating V2X communication technologies with smart cities and the Internet of Things (IoT) creates a holistic intelligent transportation ecosystem where everything works together. This connection enhances urban mobility, reduces traffic congestion, and improves the city's quality of life.

- **Smart Traffic Management:** V2X technology within smart traffic management systems makes dynamic signal adjustment, congestion management, and traffic flow optimization possible. These systems can cut down travel time and improve road safety by using real-time data from connected vehicles and infrastructure [6].
- **IoT Integration:** Connecting V2X communication to IoT devices creates an interconnected urban environment. For instance, road conditions, parking availability, and air quality can be monitored by IoT sensors, which then provide this information to V2X-enabled vehicles, thereby

enabling them to make informed decisions about their surroundings. It also supports advanced applications like smart parking lots, environmental monitoring, and efficient energy usage [29].

- Enhanced Public Transportation: V2X technology can provide real-time information to transit operators and passengers so that they are aware of what is happening around them. Bus schedule updates and train route optimizations, among other things, could help improve safety standards, for example, on buses or trains. Delays caused by inefficiencies in the current state of public transport systems management can thus be eliminated, leading to better utilization of resources within such areas [2].
- By integrating with smart cities and IoT, these technologies will enhance urban mobility, improve traffic management, and create safer transportation systems while cutting fuel consumption costs. Table I outlines the essential parameters, including latency, reliability, data rate, and communication range, necessary to meet the diverse demands of various Vehicle-to-Everything (V2X) applications. These requirements are critical to ensuring seamless communication and robust performance across different V2X scenarios, ranging from cooperative awareness to teleoperated driving [2].

III. ISO 26262 AND THE NEED FOR EXPANSION TO V2X COMMUNICATION

A. History and Development of ISO 26262

- Where ISO 26262 came from: Born from the broader IEC 61508 standard, which deals with the functional safety of electrical/electronic/programmable electronic safety-related systems, ISO 26262 is an international standard for functional safety in road vehicles. It was first published in 2011 and deals with the complexities and integration of software and hardware within automotive systems [7].
- Key points on the way to its creation: Significant steps taken in creating ISO 26262 were:
 - ✓ 2011: First release as an international standard.
 - ✓ 2018: The second edition extended to cover motorcycles, trucks, buses, and semiconductors.
 - ✓ Ongoing Updates: Continuous revision is necessary due to changing complexity levels and required safety measures within automotive systems, especially when more advanced technologies are being introduced into vehicles together with connectivity [30].

Why it matters for car makers’ functional safety efforts: ISO 26262 is essential because it ensures that the functions performed by a vehicle are safe. This can be achieved through a risk-based approach to determining what needs to be done to keep people safe while using such cars. The standard provides detailed guidance on how risks should be managed over the entire life cycle of a road vehicle from concept through decommissioning stages so that they do not materialize or if they do occur, then their effects would have been minimized already by appropriate design measures [11].

Table 1: Performance Specifications for Various V2X Scenarios [26]

Scenario Type	V2X Communication Mode	Latency Requirement	Reliability Target	Data Transfer Rate per Node (kb/s)	Effective Communication Range*
Collaborative Awareness	V2V/V2I	80 ms	88–93%	8–90	Short to medium
Collaborative Perception	V2V/V2I	4 ms	>94%	10–24,000	Short
Collaborative Operations	V2V/V2I	<5–90 ms	>98%	12–4,800	Short to medium
Safety of Vulnerable Users (SVU)	V2P	90 ms	94%	6–12	Short
Traffic Flow Optimization	V2N/V2I	>1.5 s	<92%	12–2,500	Long
Remote Control Driving	V2N	7–25 ms	>98%	>26,000	Long

*The Communication Range is Qualitatively Described as Short for < 250 m, Medium from 250 to 600 m, and Long for > 600 m.

B. ISO 26262 Scope and Structure

➤ Key Components and Structure of the Standard:

The ISO 26262 has been divided into various parts, keeping in mind its applicability along with the life cycle of automotive systems, from the concept phase to the disposal stage. They are made up of these critical components:

- Functional Safety Management – sets out the framework for managing functional safety activities.
- Concept phase – concentrates on hazard identification and risk assessment.
- Product development at system, hardware and software levels – entails requirements for system design, hardware, as well as software development.

- Production operation service and decommissioning — covers operational life cycle stages where producers shall meet functional safety requirements during production operations services until such products are withdrawn from the market or rendered useless through destruction methods that render them harmless;
- Supporting Processes – Configuration management process; Change Management Process; Documentation Process etc.
- ASIL-oriented or safety-oriented analysis: Attention is paid to safety analysis techniques along with ASIL determination [7], [31].

➤ *An Overview of Parts Within the Standard and their Importance:*

ISO 26262 addresses functional safety in different areas through its several parts which deal with various aspects related to this subject matter:

- Vocabulary — Part one provides definitions that help ensure common understanding among users about terms used within it;
- Management of Functional Safety—Part two elaborates on organizational requirements as well as responsibilities;
- Concept phase–hazard analysis is covered under section three, while risk assessment comes after that.
- System Level Product Development—The fourth part focuses on system design process steps;
- Hardware Level Product Development — Part five specifies hardware design and testing requirements;
- Software Level Product Development — Part six details software development processes including testing phases
- Life Cycle Processes for Production Operation Service & Disposal Stage – Part seven gives guidance about how best to maintain functional safety throughout the entire life cycle of the vehicle;
- Supporting Processes – Part eight talks about supporting processes such as configuration management
- ASIL-oriented or Safety-oriented analysis – methods are explained here for safety analysis and ASIL determination [30], [31].

➤ *Emphasis on Hardware and Software Safety Requirements:*

ISO 26262 lays great emphasis on ensuring that both hardware, as well as software components, meet safety standards:

- Hardware Safety Requirements—Here, guidelines are given concerning component selection; failure rate analysis; reliability estimation based on environment stress levels etc.
- Software Safety Requirements—According to this standard, the whole software development life cycle, from requirements specification through architectural design up to coding testing, verification validation, etc., should be

safe. It also requires the use of appropriate methods and tools so that reliability can be achieved [11].

- ISO 26262 offers a comprehensive approach towards achieving the highest levels of safety in all automotive system types at any point during their lifecycle.

C. *The Current Application of ISO 26262 in Automotive Safety*

➤ *Use in Modern Automotive Systems:*

Modern automotive systems have implemented ISO 26262 extensively to guarantee functional safety throughout the vehicle lifecycle stages. This criterion is used to create and verify critical systems like electric power steering, advanced driver-assistance systems (ADAS), and electronic braking systems. By following ISO 26262, car manufacturers ensure that they detect and minimize possible risks, thus reducing the chances of accidents caused by system failures [7].

➤ *Examples of Successful Applications:*

- Electric Power Steering (EPS): The application of ISO 26262 has made EPS more reliable and safer, which is essential for controlling vehicles.
- Advanced Driver-Assistance Systems (ADAS): Many features in ADAS, such as adaptive cruise control or lane-keeping assist, have been created and tested using ISO 26262 guidelines so that they can work under different conditions safely and reliably [30].
- Electronic Braking System (EBS): ISO 26262 developed EBS to meet high safety standards and prevent severe accidents resulting from failure [32].

➤ *Identification of Limitations Concerning V2X Technologies:*

Despite its wide application, ISO 26262 does not effectively address some issues regarding V2X (vehicle-to-everything) technologies. The standard fails to fully cater to intricacies brought about by V2X communication systems with diverse interoperability requirements coupled with real-time data exchange needs and cybersecurity measures that should be put in place at a higher level due to their unique nature and complexity. For instance, there is a need for more comprehensive coverage in these areas because it only considers general cases where such challenges may not always arise frequently or require detailed attention [4].

➤ *Areas that Lack Comprehensive Coverage for V2X Analysis:*

- Interoperability: ISO 26262 does not adequately deal with the integration of different communication protocols and standards necessary for achieving interoperable V2X systems.

- **Real-Time Data Processing Requirements:** The timing constraints specified by ISO 26262 are not enough to accommodate the timing needs of real-time data processing in V2X communication.
- **Cybersecurity Measures:** Although functional safety is covered under ISO 26262, it does not offer sufficient cybersecurity measures required to protect V2X communication channels against cyber-attacks.
- **Scalability and Flexibility Considerations:** There is a need for more specific guidelines on the scalability and flexibility requirements of V2X systems within dynamic vehicular networks, which may not be provided by current version(s) [20].

To make connected and autonomous vehicles a reality, these gaps must be addressed to ensure that V2X technologies are safe and reliable.

D. The Areas where ISO 26262 Should Improve V2X Communication

➤ *Limitations Analysis on V2X Communication: ISO*

26262 may have done an excellent job in traditional auto-motive systems but it falls short when it comes to addressing the needs of V2X (vehicle-to-everything) communication. The standard mainly focuses on functional safety for electrical and electronic systems in a vehicle without fully considering the complexities brought about by V2X communication technologies. Real-time data exchange between cars, infrastructure, and pedestrians is involved in V2X, hence necessitating high reliability, low latency, and robust cyber security measures, which are not well catered for under the current ISO 26262 framework [4].

➤ *Safety Challenges with Data Security, Communication Reliability, and Interoperability Issues in V2X Communications:*

- **Data Security:** Wireless channels expose the vulnerability of cyber-attacks against systems. Therefore, integrity authentication and confidentiality verification should be done to ensure that no malicious intervention occurs, thus threatening the safety of vehicles [32].
- **Communication Reliability:** Critical message delivery systems must always be reliable for collision avoidance and traffic management applications that depend on safety. However, signal degradation caused by buildings or natural features like hills and mountains, among others, can interfere with reliability; network congestion also affects reliability since more packets may be dropped due to buffer overflows [17].

- **Interoperability Issues:** Different communication standards, such as DSRC C-V2X, need to work together with old infrastructures, but lack of standardization can lead to compatibility problems, thereby slowing down the adoption rate for broader usage of these new technologies [1].

Table II presents a comprehensive comparison of the frequency bands, channelization structures, and associated standards utilized for Dedicated Short-Range Communications (DSRC) across these regions. This information is crucial for understanding the regional differences in DSRC implementation and the specific applications supported by each standard [1].

➤ *Road Safety Impacts from V2X Including Case Studies and Statistics:*

- **Reduction in Collision Rates:** Numerous studies show that collision rates can be significantly reduced by implementing V2X technology. Intersection-related crashes have gone down by 25% in urban areas with real-time traffic signal information and collision warning systems [25].
- **Enhanced Traffic Efficiency:** Optimal timing of traffic lights coupled with up-to-date traffic information through V2X helps improve flow. This has been seen through various smart city projects, where congestion levels decreased by 20%, thus reducing emissions as well [6].
- **Improved Pedestrian Safety:** A number of pilots have revealed that integrating smartphones into V2X communication systems for pedestrians (V2P) can reduce accidents among walkers; so far, the average drop rate across different trials stands at about 30% [24].

➤ *Potential Risks and Mitigation Measures Specific to V2X: Some of the Most Significant Risks and Mitigation Measures for V2X Communications are;*

- **Cybersecurity Threats:** Strong encryption should consistently be implemented alongside secure communication protocols while ensuring regular software updates are available, as these are ways to minimize cybersecurity risks. Intrusion Detection Systems (IDS) could also be employed so that any breaches detected would trigger appropriate responses immediately [32].
- **Latency in Communication:** Safety applications may need low latency, so it is essential that edge computing is utilized together with network infrastructure optimization methods to lower latencies experienced during V2X communications [28].

Table 2: DSRC Spectrum Bands and Standards in North America, Europe, and Japan

Region	Band (MHz)	Channelization	In-use or Allocated	Applications	Standard	Scope
North America	902–928	Multiple 1 MHz channels	In-use	Physical (PHY) layer communications	ASTM E2213-03	PHY layer
	5850–5925	One 10 MHz control channel, six 10 MHz service channels, and one 5 MHz reserve channel	Allocated	Road safety, public safety, and vehicle network optimization applications	IEEE 1609	Logical link control and transport layers
	5850–5925	Same as above	Allocated	ITS applications and safety services	IEEE 802.11p	PHY and medium access control (MAC) layers
Europe	5470–5725 (ITS-G5A)	Dynamic frequency selection	Allocated	ITS applications based on V2I communication	ETSI EN 302 571	Requirements for operation in the 5 GHz band
	5795–5815 (ITS-G5B)	Five 5 MHz channels	Allocated	Road transport and traffic telematics (RTTT)	ETSI EN 302 663	Requirements for operation in the ITS-G5 band
	5855–5925 (ITS-G5C)	One 10 MHz control channel, one 10 MHz service channel, and one 5 MHz reserve channel	Allocated	Non-safety applications, mainly private communications among vehicles	ETSI EN 302 571	PHY and MAC layers
Japan	755.5–764.5	Single channel (20 MHz)	Allocated	Safety applications	ARIB STD-T109	PHY, data link, and application layers
	5770–5850*	Seven quick and six slow channels (2)	Allocated	Personal information, transport communication, vehicle tolling, and navigation services	ARIB STD-T75	Application layer for the deployment of multiple DSRC services

*This band is currently used only for V2I communications with DSRC-enabled RSUs that count both the uplink and downlink transmission, based on the time division multiple access (TDMA) mode.

**This band is only for V2I communications with DSRC-enabled RSUs that act as a dynamic frequency selection (DFS) transmitter, as specified in the ETSI EN 302 663 standard.

***The ITS-G5C/RVC layer stands for inter-vehicle and roadside-to-vehicle communication layer.

The TVC-RVC vehicle applications, as defined in the ARIB-T109 standard, also specifies the required functionalities of layers 3, 4, 5, and 6 of the OSI reference model, as shown in Fig. 1.

****This band is currently in use only for V2I-related ITS applications, such as electronic toll collection.

*****The application layer, as defined in the ARIB STD-T105 and ARIB STD-T177 standards, also specifies the required functionalities of layers 1, 2, 3, 4, 5, and 6 of the OSI reference model.

- Spectrum Management Interference Control: Designating separate bands exclusively meant for Vehicle-to-Everything was one way found effective enough to mitigate interference caused within this range; advanced signal processing techniques were also considered useful, but only if backed up by regulatory measures aimed at but only if backed up by regulatory measures aimed at ensuring efficient utilization [33]. Achieving these goals would be vital in ensuring the smooth integration of V2X technologies into modern automotive systems. This will ultimately lead to better overall safety on our roads while improving traffic flow efficiency. Table III evaluates the effectiveness of various communication technologies, such as LTE-V2X, IEEE 802.11p, mm-wave, v V2X scenarios. This assessment highlights the strengths and limitations of each technology, providing

insight into their optimal applications in vehicular communication systems [2].

IV. EXPANDING ISO 26262 FOR V2X INTEGRATION

Integrating Vehicle-to-Everything (V2X) communication with existing automotive safety standards such as ISO 26262 is not just a future necessity, but an urgent one for the safety of intelligent transport systems. This part outlines the proposed changes and additional requirements for the successful integration of V2X within the ISO 26262 framework.

A. Proposed Amendments and Additions

- **New Clauses and Requirements:** Several new clauses and requirements have to be introduced to incorporate V2X communication into ISO 26262:
- **Integration of V2X-Specific Risks:** New clauses should consider singular safety risks connected with V2X systems, especially those associated with real-time communication between vehicles and infrastructure. This requires identifying potential dangers caused by delay or incorrect transmission of information that may result in accidents [7].
- **V2X Data Integrity and Security:** Given the critical role of data in V2X communication, it is

imperative that new requirements are in place to ensure its integrity and security during transmission. This involves robust protection against cyber-attacks, which can manipulate or intercept vehicle data, thereby posing serious safety hazards [32].

- **Functional Safety Verification:** The standard should include specific verification and validation processes for V2X systems. This includes ensuring that communication protocols are robust and fail-safe, especially in densely populated areas where failure to communicate could lead to catastrophic consequences [30].

Table 3: A Qualitative Assessment of the Suitability of Communication Technologies for Supporting Different V2X Use Cases

Use Case Type	LTE-V2X	IEEE 802.11p	mm-wave	Visible Light Communication (VLC)
Situational Awareness	✓✓	✓✓	✓	✗
- Vehicle to Emergency Alert	✓✓	✓✓	✗	✗
- Collision Avoidance Alert	✓✓	✓	✗	✓
Environmental Sensing	✓	✓	✓✓	✓✓
- Enhanced Vision	✓	✗	✓✓	✓
- Data Sharing Among Vehicles	✓	✓	✓	✓
Coordinated Driving	✓✓	✓	✗	✓
- Platooning	✓✓	✓	✗	✓✓
- Dense Traffic Management	✓	✗	✗	✗
- Automated Intersection Management	✓	✓	✗	✓
Pedestrian Safety	✓	✓✓	✗	✗
Traffic Optimization	✓	✗	✓✓	✗
Remote Driving	✓✓	✓	✓✓	✗

✓✓: The technology is ideal for the use case under all conditions, requiring minimal configuration.

✓: The technology supports the use case under specific conditions, such as low traffic density.

✗: The technology does not support the use case or its performance requirements

➤ Specific Safety Measures for V2X:

- **Real-Time Hazard Mitigation:** Certain safety measures must be put in place to enable real-time detection and mitigation of hazards through the use of V2X communications. For instance, vehicles should be able to talk with infrastructure elements like traffic lights or other cars, thus enabling effective emergency management and lowering the chances of collisions [23].
- **Robustness to Communication Failures:** Because V2X is used for critical safety functions, it should have a system with backup plans to keep vehicles safe even when there are no communication links or they become weak. This may involve having additional redundant systems or decision-making processes based on sensors, not only V2X inputs [33].

- **Standardized Safety Protocols:** Standardization helps achieve interoperability between various vehicles and infrastructure systems used in V2X communication. In other words, global standards should be developed that specifies how safety-critical information should be communicated and processed within V2X networks [24].

These recommendations, along with other specific safety measures, are necessary if ISO 26262 is to adequately cover the dynamic and complex nature of V2X systems so that their integration into these technologies enhances road safety.

B. Safety of Data Communication

In connected vehicles, the safety of data communication in Vehicle-to-Everything (V2X) systems is crucial. The following section describes encryption and authentication techniques for V2X communication and secure data transmission protocols.

➤ *Encryption and Authentication Methods:*

- **Public Key Infrastructure (PKI) and Symmetric Encryption:** A combination of PKI and symmetric encryption are widely recommended to secure V2X communications. PKI allows keys for encryption and authentication to be distributed across the network so that only authorized entities can access or send data. On the contrary, symmetric encryption ensures the confidentiality of information by using the same secret key between parties involved in communication. For example, Advanced Encryption Standard (AES) and PKI have been found effective in securing V2X communications because they provide both integrity and confidentiality of data [34].
- **Elliptic Curve Cryptography (ECC) and Hash Chain Cryptography:** ECC combined with hash chain cryptography has been proposed to meet lightweight, fast authentication requirements under high traffic conditions in V2X systems; this approach enables efficient message authentication while preserving privacy with minimum computational overhead considering real-time V2X applications where these methods have been shown capable of significantly reducing communication delay as well processing time [35].

➤ *Secure Data Transmission Protocols:*

- **Authenticated Datagram Protocol (ADP):** ADP is designed to secure communication in large distributed systems like V2X networks. ADP provides message authentication and optional data privacy through public-key encryption, which establishes secure channels, then single-key encryption is used to maintain the confidentiality of communicated contents, thereby ensuring that information is transmitted securely over the network as required by all security needs for V2X system such protection against unauthorized access detection prevention tampering, etc. [36].
- **Hybrid Encryption Protocols:** Hybrid encryption protocols combining block and stream encryption have been proposed for securing V2X communications. This enhances security by employing pseudo-random number encryption, mutual identification authentication, and message integrity checks, which not only ensure safe transmission of data but also make it hard for communication to be vulnerable to different types of cyber-attacks like replay man-in-the-middle among others [28].

These encryption methods, along with protocols for secure transmission, constitute necessary parts responsible for maintaining intactness, confidentiality, and genuine information within V2X communication networks, thus enabling the safe, efficient deployment of such systems.

C. *Infrastructure Safety Standards*

Ensuring safety in infrastructure components such as Road-side Units (RSUs) is crucial for implementing Vehicle-to-Everything (V2X) communication systems. This part highlights the required maintenance and operational standards for RSUs that will guarantee their reliability and safety.

➤ *Safety Measures for Roadside Unit (RSU):*

- **Optimum Placement and Signal Integrity:** The placement of an RSU is vital to maintaining reliable communication between vehicles in V2X, especially in areas with high traffic. Ensuring optimum placement minimizes chances of communication failure and guarantees continuous line-of-sight (LOS) connection, which is critical for safety-critical applications. Studies have shown that height and location directly affect signal strength and overall system performance, particularly on multi-lane highways in challenging environments [37].
- **Redundancy and Reliability:** In urban settings where a lot of data traffic may pass through these units at once, it should be designed with redundancy so that they can handle this capacity from different sources simultaneously if need be. This can involve using multiple communication channels or having fail-over mechanisms take over when one primary channel fails. Also necessary are more robust message verification protocols based on the IEEE 1609.2 standard, which helps ensure security against attacks and maintainability in such conditions [38].
- **Environmental and Operational Safety:** Considering different environmental conditions like extreme weather events, which may interfere with the signal quality or even damage hardware parts due to rusting, it becomes necessary to make them resistant to these effects by design so that signals don't get weak quickly while also enhancing durability properties too against such occasions. Additionally frequent software/firmware updates should always be performed on these devices themselves so that they continue functioning according current cyber requirements protection levels latest safe practice algorithms [39].

➤ *Maintenance and Operational Standards:*

- **Routine Maintenance Protocols:** Regular checkups must be done on these gadgets to ensure that they are still operational over long periods. This can involve things like checking for wear and tear physically on their hardware components, verifying healthy functionality communication protocols, and ensuring safety-critical software is always up-to-date, among other things. It may also help if maintenance schedules were shared across standardized environments to lower the likelihood of experiencing unexpected breakdowns [40].

- **Operational Standards Compliance:** International standards, particularly those set by bodies such as the 3rd Generation Partnership Project (3GPP) or IEEE, which focuses mainly on V2X communications, should always adhered to when dealing with RSUs because not only do they promote interoperability but also give room for future-proofing against technological advancements besides enabling broader support under traffic channel conditions [41].
- **Monitoring and Emergency Response Systems:** Faults can easily detected early enough through real-time monitoring systems integrated into them, therefore allowing switching backup units quickly or even notifying repair teams to fix any arising problem before safety becomes compromised within the V2X network [42].

It is crucial to follow strict safety precautions and maintain strong working practices so that Roadside Units (RSUs) can work effectively and safely within V2X communication networks. This will foster dependable intelligent transportation systems performance and improve general road security.

D. Integration with Existing Automotive Systems

To integrate V2X communication systems into current automotive frameworks, a harmonized approach must be taken that complies with ISO 26262 guidelines and is backward compatible with existing systems.

➤ *Harmonization with Current ISO 26262 Guidelines:*

- **Adapting ISO 26262 for V2X Systems:** Including V2X in automotive systems needs to align carefully with the functional safety standard, ISO 26262. Since it is the foundation for safety in automotive systems, extra provisions should be included in its rules to cater to complications introduced by connectivity through V2X [43]. This may involve setting new safety goals and specific hazard analysis on V2X, a system whose every component can communicate; also, all channels ought to be secure and fail-safe, as necessary during such studies. A system-of-systems approach can be adopted under the framework of ISO 26262, where risks associated with interdependency between infrastructure components are addressed, thereby increasing security in vehicle-to-vehicle networks [43].

- **Formal Verification and Compliance:** Ensuring V2X systems comply with ISO 26262 requires thorough verification at higher Automotive Safety Integrity Levels (ASILs). For ASIL C and D systems. It is recommended to use formal methods like model checking or proof assistant tools capable of verifying if given ASIL requirements are met without introducing new risks into these parts during their design phase. This should also encompass additional connectivity features that were previously neglected but are now becoming essential due to the integration process, as noted by experts who have worked on similar projects [44].

Figure 3 provides an outline of how teleoperation can be integrated with V2X technology, with the main aim being to allow remote control of autonomous cars in areas where human intervention is required but cannot be achieved directly. This feature improves safety and efficiency in self-driving especially when operating under complicated conditions that were not anticipated by the manufacturer as it facilitates immediate human-piloted judgment through strong Vehicle-to-Everything communication [2] be some vehicles which will not have adopted these new standards even after many years from now hence verification techniques must also consider those cases. For example, critical messages from these devices could be given higher priority levels during transmission over traditional channels used by earlier safety-critical applications while verifying how well different parts work together. Hybrid emulation testing might help identify problems before rolling out real-world environments [47].

By aligning V2X integration with current ISO 26262 guidelines and ensuring compatibility with existing automotive systems, industry players can facilitate smooth migration to future connected cars without compromising high levels of safety.

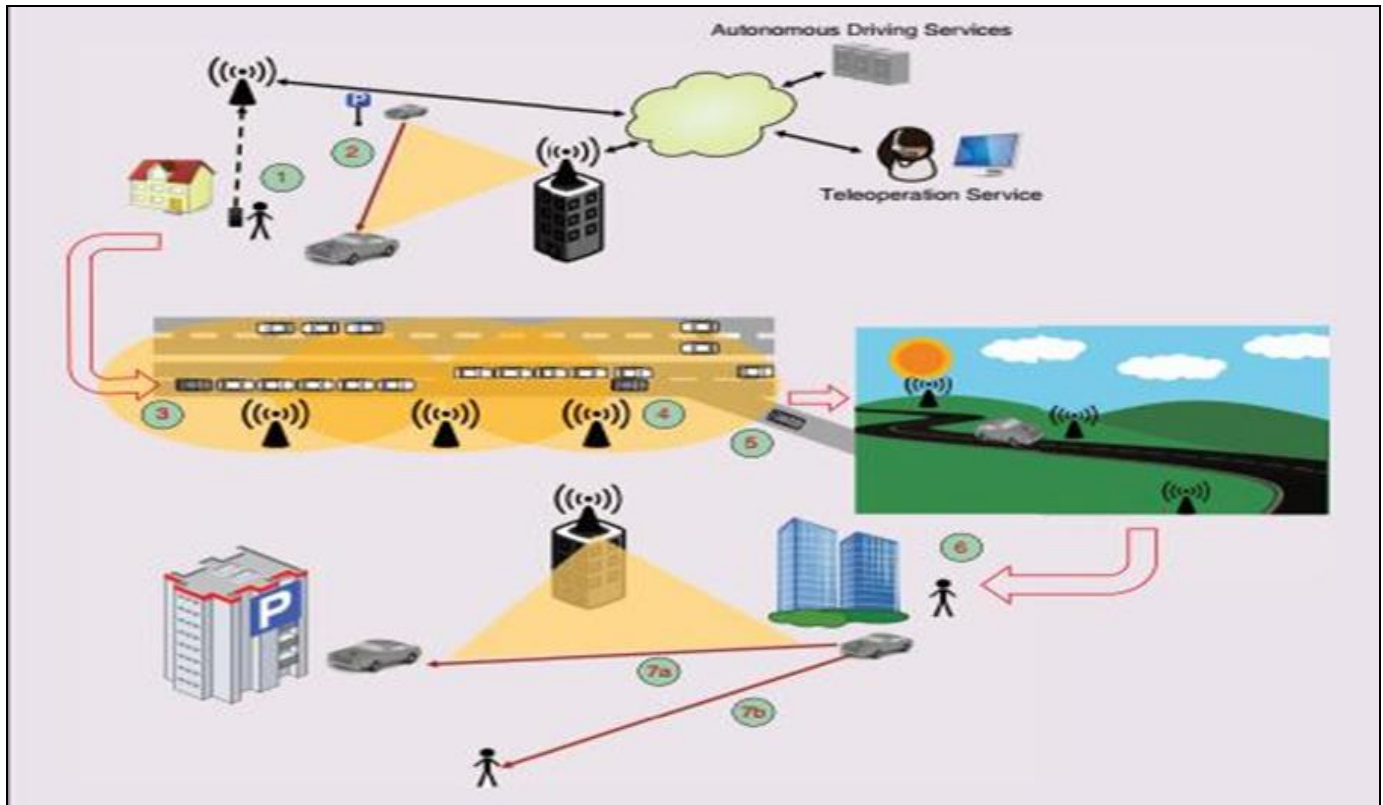


Fig 3: A Compelling Scenario for the Implementation of 5G V2X, Illustrating the Essential Requirements for Enabling Such Advancements. These Include: A) The Integration of Both Existing Use Cases (E.G., Those Referenced in [45] And [26]) and Novel Applications, And B) The Enhancement of Current Network Technologies to Ensure They Meet the Demands for Reliability, Low Latency, and Widespread Coverage Essential to These Use Cases

➤ *Ensuring Backward Compatibility:*

- **Maintaining Compatibility with Legacy Systems:** One challenge faced when integrating the V2X system lies in ensuring that new technologies can work alongside older automotive systems without causing conflicts, especially when there is no connectivity provision. This calls for a layered approach that allows the addition of V2X functionality as modular components capable of interfacing with existing Electronic Control Units (ECUs) and other subsystems within an automobile without requiring complete redesign or replacement of its architecture; such an approach is supported by ISO 26262 that allows incremental integration of new functions into safety life cycle existing system [46].

- **Adaptation and Verification Strategies:** To achieve backward compatibility, it becomes necessary to modify or enhance current safety mechanisms so they can support various features associated with V2X communication systems, but this should be done in such a way that does not break them entirely because still there may.

V. IMPLEMENTATION STRATEGIES

A. Road-map for Standard Development: A Decade Plan

Phases and Timeline for Expanding ISO 26262: Expanding ISO 26262 to cover Vehicle-to-Infrastructure (V2I) integration as part of a wider Vehicle-to-Everything (V2X) communication strategy involves several crucial phases (Figure 4). These phases must be carefully planned to align with existing automotive standards while addressing the unique challenges posed by V2X technologies.



Fig 4: ISO 26262 and V2X-V2I Integration Phases

➤ *Initial Phase: Needs Assessment and Feasibility Study (Year 1-2)*

During this phase, a comprehensive needs assessment should be conducted to identify specific safety requirements for V2I systems. Stakeholders will also review current standards, such as ISO 26262, to find out where there might be gaps or potential overlaps with new V2X communication technologies [7].

➤ *Development Phase: Drafting and Revision of Standards (Year 3-5)*

Based on the feasibility study's findings, an ad hoc task force will be formed to draft extensions to ISO 26262 that reflect functional safety requirements peculiar to V2I systems. This step involves iterative revisions informed by feedback from players in the automotive industry and pilot testing within controlled environments [30].

➤ *Validation Phase: Testing and Validation of Revised Standards (Year 6-8)*

Revised versions of ISO 26262 will undergo extensive tests, including simulations and real-world scenarios involving V2I communication. Such validation exercises have been put in place so that these standards meet the required safety integrity levels besides being applicable across various V2I applications [32].

➤ *Implementation Phase: Finalization and Industry Adoption (Year 9-10)*

Once validated successfully, necessary steps shall be taken towards finalizing the publishing of this standard, which will mark its completion. Compliance assessments will be carried out in conjunction with training programs while existing automotive software and hardware systems are being updated to support widespread adoption by the car-making industry [5].

This decade's plan establishes a roadmap for expanding ISO 26262 over V2I safety standards so that next-generation automotive technologies can meet strict safety requirements as they become part of the world's infrastructure.

B. Stakeholder Engagement: Government, Business and Academia Roles

The implementation of the ISO 26262 extended version, which covers Vehicle-to-Infrastructure (V2I) integration under Vehicle-to-Everything (V2X) communication, needs input from various stakeholders such as the government, industry, and academia, who should work in harmony. Each has a vital part to play in ensuring that these new technologies are safe, efficient, and effective.

- **Government:** Governments are supposed to create regulatory frameworks that make it mandatory for organizations to adopt standards like ISO 26262. They need to set safety requirements, encourage technical standards, and provide re-search and development funding. Additionally, they have in-frastructural roles where they ensure the compatibility of road networks and communication systems with V2I technologies [48].
- **Industry:** The automotive industry plays a critical role in implementing V2X technology since it is the leading player, including manufacturers and suppliers. Therefore, businesses dealing with this sector should integrate these features into vehicles while observing conformity with revised ISO 26262 standards. Moreover, industrial players should develop new systems for communicating with V2I, guided by safety and performance requirements [30].
- **Academia:** Foundational studies that inform standardization processes, together with technological advancements, are done by academic institutions. Students pursuing engineering courses at the tertiary level usually participate in joint ventures where their counterparts from industries and governments might also be involved, thus providing valuable insights on technicalities engaged in ensuring safety during the integration period between vehicle

infrastructure known as V2I. It also prepares them for future careers as engineers or policymakers responsible for further refining such systems [20].

- In summary, collaboration among different stakeholder groups, namely government, industry, and academia, is critical to the successful development as well as deployment of V2X technologies. The strengths brought by each party are complementary, making transportation systems for the next generation safer and more efficient.

C. Test and Verification

➤ *Methods of Simulation and Real-World Testing: To Ensure that V2X-Enabled Systems Comply with the Expanded ISO 26262 Standard, it is Necessary to Use Both Simulation and Real-World Testing Methods*

- *Simulated Tests*

Simulations are used to test V2X systems under different circumstances that may make it difficult or dangerous to recreate them in reality. Model-based design (MBD) platforms and formal analysis tools like Simulink Design Verifier are frequently employed in these simulations. These tools allow for early identification of potential failures or safety concerns that can be addressed prior to physical testing; this dramatically reduces development time and costs while guaranteeing compliance with ISO 26262 [49]. Moreover, within simulations, fault injection techniques are used to verify the system's fault tolerance and the effectiveness of safety measures [50].

- *Tests in Real Conditions*

Simulation is complemented by real-world testing, which provides information about how V2X systems operate while driving under actual conditions. This type of test includes fault injection into real vehicles aimed at evaluating anti-fault features of safety-critical components. Scenario-based testing, which is particularly useful in validating autonomous driving capabilities, often focuses on extreme cases that are crucial for the overall system's safety assurance [51].

➤ *Validation Protocols for V2X Enabled Systems: The Validation Procedures Included In ISO 26262 Applicable To V2X-Enabled Systems Should Cover All Components As Well As Their Interactions So That Required Levels Of Safety Can Be Met.*

- *Structured Validation*

Structured validation implies a systematic model-based approach integrating both OEM & supplier verification/validation activities throughout the development life cycle, starting from system design up to final validation. This would ensure compliance with all safety requirements during every stage of the product realization process. Using Unified Modeling Language (UML) models for

planning/documenting such activities allows for rigorous verification of safety-relevant constraints and requirements [52].

- *Scenario-Based Validation*

Scenario-based testing is indispensable when validating the functionality of automated driving systems and V2X technologies. It concentrates on evaluating how well the system performs under different scenarios, both commonly encountered and scarce ones. Such a test approach ensures that vehicles can interact with infrastructure safely across various conditions in real-life situations where they may be exposed to dangerous environmental elements [53].

These methods ensure compliance with ISO26262 by V2X-enabled systems through simulation tests, real-world trials, and strict validation protocols.

D. Case Studies and Pilot Projects

A. *Examples of Implementation in Different Regions: Regions all over the World have Piloted V2X Communication Systems while Extending ISO 26262 Standards to Cover Vehicle-to-Infrastructure (V2I) Integration.*

➤ *Germany*

Within V2X systems, German automotive manufacturers and suppliers have been pioneers in applying ISO 26262. For example, a notable pilot project by a leading German car manufacturer integrated ISO 26262 into its development processes. This project ensured functional safety in the integration of V2X systems within vehicles through safety analysis and model-based approaches. The pilot also showed that it is adequate to move from a document-centric approach toward more dynamic models-based development [54].

➤ *United States*

Several pilots were launched in America to determine if V2X communication systems can work safely under the strict regulations posed by ISO 26262. These projects partnered with government bodies, industries, and academic institutions to develop real-world validated V2X technology development test cases. In Michigan, where connected cars were being tested, v2i systems had to be evaluated for their compliance with safety standards and how well they could integrate with existing infrastructure [11].

➤ *Japan*

Japan has deployed many urban-based V2X installations, especially around Tokyo city, where intersections and other critical traffic points are fitted with V2I communications integrated into the city's infrastructure. Lessons learned from these pilot studies indicate that localized tests are crucial in ensuring that such systems meet international safety requirements like iso 26262, especially

when dealing with traffic-dense areas having complicated road networks [55].

B. Lessons Learned and Best Practices: The Following Sections Detail Some Key Insights Gained from These Pilots Regarding How Best to Implement V2Is Under ISO26262 Standards Across Different Regions Worldwide.

➤ *Integration of Model-Based Development*

One of the major lessons learned is that we should incorporate model-based development (MBD) techniques into the process of implementing V2X. This allows for early detection of potential safety issues and ensures rigorous testing of V2I systems at different stages during development. For instance, German pilots showed how MBD could streamline the safety validation process, improving quality outcomes [54].

➤ *Collaboration Between Stakeholders*

Successful V2X deployments require close collaboration between government agencies, industry bodies, and academic institutions. Such partnerships are essential in developing universal traffic safety standards that cater to regions with different traffic conditions worldwide. US projects also pointed out the need for joint efforts toward standardizing V2I communication protocols besides ensuring their compatibility with existing infrastructure [11].

➤ *Localized Testing and Adaptation*

Localized tests are important because they enable us to address unique challenges in different environments. For example, Japanese pilots highlighted the need for designing tailor-made urban-oriented V2Is capable of providing enhanced protection within complex metropolitan settings characterized by high-volume multi-modal transport operations [55].

In conclusion, these pilot projects provide valuable insights into how best to implement V2X under ISO 26262 through lessons such as the model-based development approach, stakeholder collaboration requirements, and localization needs based on specific environmental conditions.

VI. BENEFITS AND CHALLENGES

A. Benefits

➤ *Better Safety and Reliability of V2X Systems: When ISO*

- 26262 is expanded to cover V2X communication, it improves the safety and reliability of such systems by ensuring that strict safety rules are applied for vehicle-to-vehicle and vehicle-to-infrastructure exchanges. Standardizing safety protocols within V2X

communications mitigates potential risks caused by data transmission errors or cyber threats, thus making the environment for communicating between vehicles more secure and dependable [4].

- Increased public confidence in V2X technologies: Incorporating ISO 26262 standards into V2X technologies may increase public trust in these systems. Users need some level of assurance that they can trust this technology because its implementation involves their lives; therefore, high levels of safety must be maintained throughout its usage. Public awareness about what should be done when using these devices should also match actual security measures put in place, so as not to discourage people from adopting them [56].
- Complementarity with existing safety frameworks: Integrating ISO 26262 with V2X communication frameworks facilitates compatibility with current automotive safety standards. This implies that apart from meeting all necessary pre-cautions under these protocols, other benefits will be realized by considering ongoing developments made on automotive safety standards while designing V2X systems. This is important because different types of intelligent transport systems have varying levels of robustness in terms of their protection mechanisms, thus posing a challenge to achieving uniformity across the board regarding this aspect alone [24].

ISO 26262 extension for V2X communication systems has many advantages, including safety aspects, gaining confidence among the general public, and fitting within already existing frameworks, which contribute greatly to wider adoption coupled with increased dependability in the utilization of such technologies.

B. Challenges

- Problems of a Technical and Logistical Nature during Typical Application: Implementing ISO 26262 standards for V2X communication has many technical and logistical challenges. Within an established safety framework, it is required to integrate vehicle-to-vehicle (V2V) and vehicle-to-infrastructure (V2I) communication by overcoming some technical barriers which involve the synchronization of multiple communication protocols, ensuring backward compatibility as well as coping with diverse infrastructure capabilities across different regions. What makes these tasks complex is that they have to be performed in real-time while maintaining low-latency communication and dealing with vast volumes of data produced by V2X systems [28].
- Implications on Manufacturers' and Infrastructure Providers' Financial Resources : The cost implications of expanding ISO 26262 up to V2X systems are heavy on both manufacturers as well as infrastructure providers. High expenditure levels may be incurred due to new

equipment requirements, extensive testing needs, and retrofitting existing infrastructures for compliance with heightened safety standards. Manufacturers will have to invest in coming up with technologies that are not only new but also validated; on the other hand, road networks should be upgraded by sensitizing them, among other things, thus making it costly for suppliers [24]. It might, therefore, take longer before these technologies are widely adopted, especially in less economically developed areas.

- **Catering for the Dynamic Nature of V2X Technology Developments :** The relevance of the ISO 26262 standard could quickly become outdated, and keeping pace with the ever-changing nature posed by advancements in V2X technology becomes another task altogether. Whenever there is an introduction or emergence of any new technology, such a standard must continuously revise itself to bridge any gap occasioned by increased risks besides accommodating more recent improvements within communication protocols and sensor technologies alongside vehicle automation systems. Accordingly, this need for constant review coupled with corresponding adjustment may overstretch regulatory organizations and industry players who should jointly ensure that these benchmarks are always up-to-date without causing any deployment delays [57].

The challenges to extending ISO 26262 for V2X systems are many: they include significant technical hurdles, high implementation costs, and the need for continuous adaptation to fast-changing technology. These difficulties must be addressed in order to successfully incorporate secure and reliable V2X communication into automotive systems.

VII. DISCUSSION: FUTURE DIRECTIONS AND RESEARCH OPPORTUNITIES

A. *Improvements in V2X Technologies: New Concepts and Inventions*

Vehicle-to-everything (V2X) technologies are changing very fast these days, mainly because of improvements in communication systems, integration of self-driving cars, and demand for intelligent transport systems (ITS). The Internet of Vehicles (IoV) is a major trend in which traditional V2X technologies are being redefined to suit more intricate vehicular applications such as cooperative autonomous driving and smart cities [58].

Other developments include the integration of advanced cellular technologies like 5G, which provides better communication reliability with low latency and wide bandwidth, thus allowing real-time vehicle-to-infrastructure interactions [4]. Also, there has been development on cooperative sensing capability coupled with maneuvering so that data from local sensors can be shared among autonomous vehicles, thus improving traffic safety as well as efficiency [59].

Another area of interest involves combining V2X systems with Artificial Intelligence (AI), edge computing, and the Internet of Things (IoT), among other emerging fields. For instance, these are key enablers for smarter vehicle networks, which are expected to be highly autonomous and connected at some point in the future, according to [60].

The continuous growth witnessed within V2X technology, mainly through integration with 5G, IoV, and AI lays the foundations for intelligent transportation. Henceforth, safer environments during travel will be possible while also increasing efficiency levels within different parts of the network, even if most cars become automated.

B. *Continuous Safety Standards Improvement: Feedback Loop for Updating Standards*

A dynamic automotive environment created by V2I (vehicle-to-infrastructure) communication systems and other Vehicle-to-Everything (V2X) technologies powered by ISO 26262 requires constant enhancements of safety standards as part of its adaptation process. The most crucial measure is providing field data-based, real-time, updated standard adjustments through a robust feedback mechanism considering new studies and technological progress.

One suggestion for improving ISO 26262 is adding a “Safety Manager Review” network, which would mirror the Flight Readiness Review used in the Aerospace & Aviation industry. This network should allow better communication between different organizations involved in the safety lifecycle, leading to quicker identification and resolution of safety issues and ensuring that safety functions effectively meet quantitative targets [12].

Moreover, the structured approach towards safety requirements also improves the feedback loop, ensuring that updates made on this standard are informed by their practicality. In order to achieve this, there should be continuous collaboration among manufacturers with regulatory bodies coupled with research institutions to establish uniformity while refining Automotive Safety Integrity Level (ASIL) assessments hence eliminating subjectivity across industries [61].

To keep up with fast-changing V2X technology, continuous improvement of ISO 26262 through cross-industry collaboration based on data-driven updates supported by standardized assessment practices is vital for keeping abreast of these developments in automotive safety standards systems.

C. *Cross-Industry Collaborations: Partnerships between the Automotive and Telecommunication Industries*

The integration of Vehicle-to-Infrastructure (V2I) communication and broader Vehicle-to-Everything (V2X) technologies calls for strong collaboration across industries,

especially between the automotive sector and the telecommunications industry. Such collaborations are necessary for the successful implementation of advanced communication systems like 5G, which is key in supporting the real-time exchange of data between vehicles and infrastructure. One area where these partnerships have shown potential is in developing communication standards that both sectors can use. For instance, automakers partnering with telecom companies have created LTE-based V2X systems that utilize existing cellular network infrastructure to enable vehicle-to-infrastructure communication [4]. This cooperation also involves integrating 5G technology, which promises lower latency periods coupled with improved reliability features critical for autonomous driving safety applications.

Additionally, cross-sectorial efforts such as the Automotive Knowledge Alliance bring together experts from different domains, including Functional Safety (ISO 26262) and Lean Six Sigma, among others, so as to enhance the development of safety-critical systems within this context. The alliance provides a platform for sharing information and adopting best practices from various industries, leading to safer and more dependable automotive systems [62].

Inter-industrial relations involving automotive and telecom-munication enterprises play a significant role in advancing V2X technologies. This ensures that communication systems satisfy stringent requirements set by modern vehicle networks while promoting innovative approaches towards safety-critical applications.

D. International Standardisation: Attempts to Align ISO 26262 with Worldwide Safety Standards

Harmonizing global vehicle safety standards is necessary to ensure that all cars meet uniform safety requirements across various regions. As the primary functional safety standard for road vehicles, ISO 26262 has undergone several steps in its journey towards this goal by converging with other international safety standards and best practices.

One of the most critical undertakings so far involves periodically reviewing and updating ISO 26262 to incorporate new safety needs as well as aligning it with other worldwide standards. For example, during the development process of the second edition, the scope was extended to cater to more categories of vehicles while integrating fresh guidelines on failed operational systems, which was prompted by increased complexity levels in modern-day automobiles [14].

Also, much attention has been given to aligning ISO 26262 with generic functional safety standards such as IEC 61508. This move helps ensure that what is contained in ISO 26262 about safe practice can be applied elsewhere within different industries where there are critical systems involving

human lives, thus fostering a common approach towards protection against hazards arising from these functions [63].

It is, however, worth noting that still more work needs to be done regarding, among others, possible connections between this automotive cybersecurity framework and security standardization efforts like those embodied by ISO/IEC 15408 or even recognition of the increasing importance attached to cyber security for inter-connected autonomous vehicles under our roads today [64]. The idea behind merging these two areas is the creation of an integrated approach that caters to both functional safety requirements as well as protection against system hacking threats, given the current environment characterized by high-level interaction between different components forming part of a single unit capable self-driving along highways without any intervention from humans.

In conclusion, it can never be overemphasized how important it is to harmonize ISO 26262 with world safety standards, but this should not come at the expense of making them more robust, especially considering emerging risks within our industry.

VIII. CONCLUSION

ISO 26262 is being integrated with V2X communication systems to improve the reliability and safety of complex vehicle networks. This is in recognition that the functional safety standard must be expanded to accommodate the dynamic nature of V2X environments. The research points out several advantages that can be derived from this integration, such as increased safety measures and better traffic control. It identifies gaps within ISO 26262 regarding V2X integration, including cybersecurity, real-time data processing, and interoperability.

These findings are contextualized against an evolving transport landscape where V2X technology is increasingly pivotal. The study's recommendations for ISO 26262 extension are compared against current standards to show continuity and innovation in advancing vehicular safety protocols. It emphasizes improved standards' potential to substantially lower auto-motive accidents and enhance traffic efficiency. The discussion reflects how these extended standards could act as catalysts for more robust integrated global vehicular communication systems.

The researchers acknowledge their restrictions, particularly due to the rapid pace at which technology changes within V2X communication, thus possibly overtaking efforts toward standardization. It is crucial that additional research be carried out to investigate advanced cryptographic measures aimed at beefing up security in V2X systems, besides evaluating impacts brought about by emerging technologies like 5G on the effectiveness and dependability of

vehicle communications. This research is of utmost importance and should be prioritized, emphasizing the urgency of the matter.

Extending ISO 26262 with V2X aligns with modern intelligent transport system technological imperatives and significantly improves safety levels across different vehicles networked together. ISO 26262's potential to adapt itself to such developments reassures us about its adaptability, opening up exciting prospects for future vehicular safety standards. This marks a significant milestone toward the worldwide realization of fully integrated, safe, and efficient transportation systems, providing reassurance about the adaptability of ISO 26262.

REFERENCES

- [1]. Abboud, H. A. Omar, and W. Zhuang, "Interworking of DSRC and Cellular Network Technologies for V2X Communications: A Survey," *IEEE Transactions on Vehicular Technology*, vol. 65, no. 12, pp. 9457–9470, Dec. 2016, conference Name: IEEE Transactions on Vehicular Technology. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7513432>
- [2]. M. Boban, A. Kousaridas, K. Manolakis, J. Eichinger, and W. Xu, "Connected Roads of the Future: Use Cases, Requirements, and Design Considerations for Vehicle-to-Everything Communications," *IEEE Vehicular Technology Magazine*, vol. 13, no. 3, pp. 110–123, Sep. 2018, conference Name: IEEE Vehicular Technology Magazine. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/8410403>
- [3]. A. Serin, A. Boyaci, A. Özpınar, and S. Yarkan, "An IEEE 802.11x Implementation for V2X Communications Towards IoT and Big Data," in *International Telecommunications Conference*, A. Boyaci, A. R. Ekti, Aydin, and S. Yarkan, Eds. Singapore: Springer, 2019, pp. 177–188.
- [4]. S. Chen, J. Hu, Y. Shi, Y. Peng, J. Fang, R. Zhao, and L. Zhao, "Vehicle-to-Everything (v2x) Services Supported by LTE-Based Systems and 5G," *IEEE Communications Standards Magazine*, vol. 1, no. 2, pp. 70–76, 2017, conference Name: IEEE Communications Standards Magazine. [Online]. Available: <https://ieeexplore.ieee.org/document/7992934>
- [5]. H. Seo, K.-D. Lee, S. Yasukawa, Y. Peng, and P. Sartori, "LTE evolution for vehicle-to-everything services," *IEEE Communications Magazine*, vol. 54, no. 6, pp. 22–28, Jun. 2016, conference Name: IEEE Communications Magazine. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7497762>
- [6]. X. Shi, "More than smart pavements: connected infrastructure paves the way for enhanced winter safety and mobility on highways," *Journal of Infrastructure Preservation and Resilience*, vol. 1, no. 1, p. 13, Nov. 2020. [Online]. Available: <https://doi.org/10.1186/s43065-020-00014-x>
- [7]. B. Schätz, "Certification of Embedded Software – Impact of ISO DIS 26262 in the Automotive Domain," in *Leveraging Applications of Formal Methods, Verification, and Validation*, T. Margaria and Steffen, Eds., vol. 6415. Berlin, Heidelberg: Springer, 2010, pp. 3–3. [Online]. Available: https://doi.org/10.1007/978-3-642-16558-0_2
- [8]. D. D. Ward and I. Ibarra, "Development Phase in Accordance with ISO 26262," in *8th IET International System Safety Conference incorporating the Cyber Security Conference 2013*, Oct. 2013, place: Cardiff, UK. [Online]. Available: <https://doi.org/10.1049/cp.2013.1718>
- [9]. S.-H. Jeon, J.-H. Cho, Y. Jung, S. Park, and T.-M. Han, "Automotive hardware development according to ISO 26262," in *13th International Conference on Advanced Communication Technology (ICACT2011)*, Feb. 2011, pp. 588–592, iSSN: 1738-9445. [Online]. Available: <https://ieeexplore.ieee.org/document/5745882>
- [10]. M. Hillenbrand, M. Heinz, N. Adler, K. D. Müller-Glaser, J. Matheis, and C. Reichmann, "ISO DIS 26262 in the Context of Electric/Electronic Architecture," in *Architecting Critical Systems (ISARCS 2010)*, ser. Lecture Notes in Computer Science, vol. 6150, Jun. 2010, pp. 179–192. [Online]. Available: https://doi.org/10.1007/978-3-642-13556-9_11
- [11]. A. B. Hocking, J. Knight, M. A. Aiello, and S. Shiraishi, "Arguing Software Compliance with ISO 26262," in *Proceedings of the 2014 IEEE International Symposium on Software Reliability Engineering Workshops*, Nov. 2014, pp. 1–6. [Online]. Available: <https://doi.org/10.1109/ISSREW.2014.6983843>
- [12]. P. Stirgwolt, "Management of Safety as Per ISO 26262 Standard," in *2013 Proceedings Annual Reliability and Maintainability Symposium (RAMS)*, Jan. 2013. [Online]. Available: <https://doi.org/10.1109/RAMS.2013.6517758>
- [13]. M. Conrad, G. Sandmann, and P. Munier, "Software Tool Qualification According to ISO 26262," in *SAE 2011 World Congress & Exhibition*, Apr. 2011. [Online]. Available: <https://doi.org/10.4271/2011-01-1005>
- [14]. G. Griessnig and A. Schnellbach, "Development of the 2nd Edition of the ISO 26262," in *Systems, Software and Services Process Improvement*, Stolfa, S. Stolfa, R. V. O'Connor, and R. Messnarz, Eds. Cham: Springer International Publishing, 2017, pp. 535–546.

- [15]. T. Yoshizawa, D. Singelée, J. T. Muehlberg, S. Delbruel, A. Taherkordi, Hughes, and B. Preneel, “A Survey of Security and Privacy Issues in V2X Communication Systems,” *ACM Comput. Surv.*, vol. 55, no. 9, pp. 185:1–185:36, Jan. 2023. [Online]. Available: <https://doi.org/10.1145/3558052>
- [16]. T. Yoshizawa and B. Preneel, “Survey of Security Aspect of V2X Standards and Related Issues,” *Journal of Communications and Information Networks*, vol. 4, no. 2, pp. 101–112, Jun. 2019. [Online]. Available: <https://doi.org/10.1007/s41650-019-0022-x>
- [17]. P. Dhawankar, P. Agrawal, B. Abderezzak, O. Kaiwartya, K. Busawon, and M. S. Raboaca, “Design and Numerical Implementation of V2X Control Architecture for Autonomous Driving Vehicles,” *Mathematics*, vol. 9, no. 14, p. 1696, Jan. 2021, number: 14 Publisher: Multidisciplinary Digital Publishing Institute. [Online]. Available: <https://www.mdpi.com/2227-7390/9/14/1696>
- [18]. Z. Naghsh and S. Valaee, “Conflict-Free Scheduling in Cellular V2X Communications,” *IEEE/ACM Transactions on Networking*, vol. 29, no. 1, pp. 106–119, 2021.
- [19]. O. Sander, C. Roth, B. Glas, and J. Becker, “Towards Design and Integration of a Vehicle-to-X Based Adaptive Cruise Control,” in *Proceedings of the FISITA 2012 World Automotive Congress*, 2013, pp. 87–99. [Online]. Available: https://doi.org/10.1007/978-3-642-33838-0_8
- [20]. A. Costandoiu and M. Leba, “Convergence of V2X Communication Systems and Next Generation Networks,” in *IOP Conference Series: Materials Science and Engineering*, vol. 477, Jun. 2019, p. 012052. [Online]. Available: <https://doi.org/10.1088/1757-899X/477/1/012052>.
- [21]. M. Muhammad and G. A. Safdar, “Survey on existing authentication issues for cellular-assisted V2X communication,” *Vehicular Communications*, vol. 12, pp. 50–65, Apr. 2018. [Online]. Available: <https://www.sciencedirect.com/science/article/pii/S2214209617302267>
- [22]. J. Santa, F. Pereñíguez, J. C. Cano, A. F. Skarmeta, C. T. Calafate, and P. Manzoni, “Comprehensive Vehicular Networking Platform for V2I and V2V Communications within the Walkie-Talkie Project,” *International Journal of Distributed Sensor Networks*, vol. 9, no. 7, p. 676850, Jul. 2013, publisher: SAGE Publications. [Online]. Available: <https://doi.org/10.1155/2013/676850>
- [23]. K. Liu, J. K.-Y. Ng, J. Wang, V. C. S. Lee, W. Wu, and S. H. Son, “Network-Coding-Assisted Data Dissemination via Cooperative Vehicle-to-Vehicle-/Infrastructure Communications,” *IEEE Transactions on Intelligent Transportation Systems*, vol. 17, no. 6, pp. 1509–1520, Jun. 2016, conference Name: IEEE Transactions on Intelligent Transportation Systems. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7330008>
- [24]. E. Cinque, F. Valentini, A. Persia, S. Chiochio, F. Santucci, and M. Pratesi, “V2X Communication Technologies and Service Requirements for Connected and Autonomous Driving,” in *2020 AEIT International Conference of Electrical and Electronic Technologies for Automotive (AEIT AUTOMOTIVE)*, Nov. 2020, pp. 1–6. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9307388>
- [25]. T. Petrov, P. Pocta, and T. Kovacicova, “Benchmarking 4G and 5G-Based Cellular-V2X for Vehicle-to-Infrastructure Communication and Urban Scenarios in Cooperative Intelligent Transportation Systems,” *Applied Sciences*, vol. 12, no. 19, p. 9677, Jan. 2022, number: 19 Publisher: Multidisciplinary Digital Publishing Institute. [Online]. Available: <https://www.mdpi.com/2076-3417/12/19/9677>
- [26]. 3GPP, “Study on Enhancement of 3GPP Support for 5G V2X Services (Release 15),” 3rd Generation Partnership Project, Sophia Antipolis, France, Technical Report 3GPP TR 22.886 V1.0.0, Nov. 2016.
- [27]. M. Ferreira, L. Damas, H. Conceição, P. M. d’Orey, R. Fernandes, P. Steenkiste, and P. Gomes, “Self-automated parking lots for autonomous vehicles based on vehicular ad hoc networking,” in *2014 IEEE Intelligent Vehicles Symposium Proceedings*, Jun. 2014, pp. 472–479, iSSN: 1931-0587. [Online]. Available: <https://ieeexplore.ieee.org/document/6856561>.
- [28]. Y. Zhong, T. Bi, J. Wang, J. Zeng, Y. Huang, T. Jiang, Q. Wu, and Wu, “Empowering the V2X Network by Integrated Sensing and Communications: Background, Design, Advances, and Opportunities,” *IEEE Network*, vol. 36, no. 4, pp. 54–60, Jul. 2022, conference Name: IEEE Network. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9919739>.
- [29]. M. Zrikem, I. Hasnaoui, and R. Ellassali, “Vehicle-to-Blockchain (V2B) Communication: Integrating Blockchain into V2X and IoT for Next-Generation Transportation Systems,” *Electronics*, vol. 12, no. 16, p. 3377, Jan. 2023, number: 16 Publisher: Multidisciplinary Digital Publishing Institute. [Online]. Available: <https://www.mdpi.com/2079-9292/12/16/3377>.

- [30]. P. Johannessen, Halonen, and O. Örsmark, “Functional Safety Ex-tensions to Automotive SPICE According to ISO 26262,” in *Software Process Improvement and Capability Determination*, R. V. O’Connor, Rout, F. McCaffery, and A. Dorling, Eds. Berlin, Heidelberg: Springer, 2011, pp. 52–63.
- [31]. I. ISO, “26262: 2018: Road vehicles—Functional safety,” *British Standards Institute*, vol. 12, 2018.
- [32]. S. Woo, H. J. Jo, I. S. Kim, and D. H. Lee, “A Practical Security Architecture for In-Vehicle CAN-FD,” *IEEE Transactions on Intelligent Transportation Systems*, vol. 17, no. 8, pp. 2248–2261, Aug. 2016, conference Name: *IEEE Transactions on Intelligent Transportation Systems*. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7435304>
- [33]. J. Ahn, Y. Y. Kim, and R. Y. Kim, “A Novel WLAN Vehicle-To-Anything (V2X) Channel Access Scheme for IEEE 802.11p-Based Next-Generation Connected Car Networks,” *Applied Sciences*, vol. 8, no. 11, p. 2112, Nov. 2018, number: 11 Publisher: *Multidisciplinary Digital Publishing Institute*. [Online]. Available: <https://www.mdpi.com/2076-3417/8/11/2112>
- [34]. K. Tu, “Communications Link Layer Security,” in *2006 International Conference on Communication Technology*, Nov. 2006, pp. 1–[Online]. Available: <https://ieeexplore.ieee.org/abstract/document/4146285>
- [35]. S. A. A. Hakeem, M. A. A. El-Gawad, and H. Kim, “Comparative Experiments of V2X Security Protocol Based on Hash Chain Cryptography,” *Sensors*, vol. 20, no. 19, p. 5719, Jan. 2020, number: Publisher: *Multidisciplinary Digital Publishing Institute*. [Online]. Available: <https://www.mdpi.com/1424-8220/20/19/5719>
- [36]. D. P. Anderson, D. Ferrari, P. V. Rangan, and B. Sartirana, “A Protocol for Secure Communication in Large Distributed Systems,” *University of California at Berkeley, USA, Technical Report*, Jan. 1987.
- [37]. A. Chattopadhyay, A. Chandra, and C. Bose, “Impact of RSU Height on 60 GHz mmWave V2I LOS Communication in Multi-lane Highways,” in *2021 IEEE 93rd Vehicular Technology Conference (VTC2021-Spring)*, Apr. 2021, pp. 1–5, iISSN: 2577-2465. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9448835>
- [38]. S. Lee, H. Seo, B. Chunng, J. Choi, H. Kwon, and H. Yoon, “OpenCL Based Implementation of ECDSA Signature Verification for V2X Com-munication,” in *Advanced Multimedia and Ubiquitous Engineering*, J. J. Park, V. Loia, K.-K. R. Choo, and G. Yi, Eds. Singapore: Springer, 2019, pp. 711–716.
- [39]. N. Ferreira, T. Meireles, and J. A. Fonseca, “An RSU coordination scheme for WAVE safety services support,” in *2009 IEEE Conference on Emerging Technologies & Factory Automation*, Sep. 2009, pp. 1–4, iISSN: 1946-0759. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/5347231>
- [40]. L. Miao, S.-C. Chien, F.-C. Chang, and K.-L. Hua, “C-V2X Solution for SPAT Application and Maintenance,” in *2022 IEEE International Conference on Consumer Electronics - Taiwan*, Jul. 2022, pp. 405–406, iISSN: 2575-8284. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9869156>
- [41]. C. Anzola-Rojas, J. C. Aguado, R. J. Durán Barroso, I. De Miguel, N. Merayo, P. Fernández, R. M. Lorenzo, and E. J. Abril, “RSU Placement Considering V2X Services Requirements and Available Radio Resources,” in *2023 33rd International Telecommunication Networks and Applications Conference*, Nov. 2023, pp. 218–221, iISSN: 2474-154X. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/10368529>
- [42]. M. Carvalhosa, J. Almeida, and J. Ferreira, “Poster: Road Sensor Messages for V2X Scenarios,” in *2023 IEEE Vehicular Networking Conference (VNC)*, Apr. 2023, pp. 169–170, iISSN: 2157-9865. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/10136282>
- [43]. A. K. Saberi, E. Barbier, F. Benders, and M. van den Brand, “On functional safety methods: A system of systems approach,” in *2018 Annual IEEE International Systems Conference (SysCon)*, Apr. 2018, pp. 1–6, iISSN: 2472-9647. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/8369598>
- [44]. G. Bahig and A. El-Kadi, “Formal Verification of Automotive Design in Compliance With ISO 26262 Design Verification Guidelines,” *IEEE Access*, vol. 5, pp. 4505–4516, 2017, conference Name: *IEEE Access*. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7879875>
- [45]. ETSI, “Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Definitions,” *European Telecommunications Standards Institute, Sophia Antipolis, France, Technical Report ETSI TR 102 638 V1.1.2*, 2015.
- [46]. H. Guo, J. Liu, S. Yu, and J. Li, “Iso 26262 Impact on Development of Powertrain Control System,” in *Proceedings of the FISITA 2012 World Automotive Congress*. Berlin, Heidelberg: Springer, 2013, pp. 705–715.

- [47]. N. V. Alluri, P. R. Sykam, and H. Narayanaswamy, "Hybrid emulation approach in ISO 26262 compliant unit test process," in 2019 IEEE International Test Conference India (ITC India), Jul. 2019, pp. 1–7. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/8979727>.
- [48]. Z. MacHardy, A. Khan, K. Obana, and S. Iwashina, "V2X Access Technologies: Regulation, Research, and Remaining Challenges," *IEEE Communications Surveys & Tutorials*, vol. 20, no. 3, pp. 1858–1877, 2018, conference Name: IEEE Communications Surveys & Tutorials. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/8300313>
- [49]. S. Khastgir, G. Dhadyalla, and P. Jennings, "Incorporating ISO 26262 Concepts in an Automated Testing Toolchain Using Simulink Design Verifier™," *SAE International Journal of Passenger Cars - Electronic and Electrical Systems*, vol. 9, no. 1, pp. 59–65, Apr. 2016, publisher: SAE International. [Online]. Available: <https://saemobilus.sae.org/articles/incorporating-iso-26262-concepts-automated-testing-toolchain-using-simulink-design-verifier-2016-01-0032>
- [50]. L. Pintard, M. Leeman, A. Ymlahi-Ouazzani, J.-C. Fabre, K. Kanoun, and M. Roy, "Using Fault Injection to Verify an AUTOSAR Application According to the ISO 26262," in SAE 2015 World Congress & Exhibition, ser. Journal Articles from SAE 2015 World Congress & Exhibition. Detroit, United States: SAE International, Apr. 2015. [Online]. Available: <https://hal.science/hal-01221422>
- [51]. D. Rao, P. Pathrose, F. Huening, and J. Sid, "An Approach for Validating Safety of Perception Software in Autonomous Driving Systems," in *Model-Based Safety and Assessment*, Y. Papadopoulos, K. Aslansefat, Katsaros, and M. Bozzano, Eds. Cham: Springer International Publishing, 2019, pp. 303–316.
- [52]. K. Beckers, I. Côté, T. Frese, D. Hatebur, and M. Heisel, "A Structured Validation and Verification Method for Automotive Systems Considering the OEM/Supplier Interface," in *Computer Safety, Reliability, and Security*, F. Koornneef and C. van Gulijk, Eds. Cham: Springer International Publishing, 2015, pp. 90–108.
- [53]. C. Neurohr, L. Westhofen, T. Henning, T. de Graaff, E. Möhlmann, and Böde, "Fundamental Considerations around Scenario-Based Testing for Automated Driving," in 2020 IEEE Intelligent Vehicles Symposium (IV), Oct. 2020, pp. 121–127, iSSN: 2642-7214. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9304823>
- [54]. M. Born, J. Favaro, and O. Kath, "Application of ISO DIS 26262 in practice," in *Proceedings of the 1st Workshop on Critical Automotive applications: Robustness & Safety*, ser. CARS '10. New York, NY, USA: Association for Computing Machinery, Apr. 2010, pp. 3–6. [Online]. Available: <https://doi.org/10.1145/1772643.1772645>
- [55]. I. Stürmer, E. Salecker, and H. Pohlheim, "Reviewing Software Models in Compliance with ISO 26262," in *Computer Safety, Reliability, and Security*, F. Ortmeier and P. Daniel, Eds. Berlin, Heidelberg: Springer, 2012, pp. 258–267.
- [56]. M. A. Sharafsaleh, J. VanderWerf, J. A. Misener, and S. E. Shladover, "Implementing Vehicle-Infrastructure Integration: Real-World Challenges," *Transportation Research Record*, vol. 2086, no. 1, pp. 124–132, Jan. 2008, publisher: SAGE Publications Inc. [Online]. Available: <https://doi.org/10.3141/2086-15>
- [57]. S. Gyawali, S. Xu, Y. Qian, and R. Q. Hu, "Challenges and Solutions for Cellular Based V2X Communications," *IEEE Communications Surveys & Tutorials*, vol. 23, no. 1, pp. 222–255, 2021, conference Name: IEEE Communications Surveys & Tutorials. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/9217500>
- [58]. H. Zhou, W. Xu, J. Chen, and W. Wang, "Evolutionary V2X Technologies Toward the Internet of Vehicles: Challenges and Opportunities," *Proceedings of the IEEE*, vol. 108, no. 2, pp. 308–323, Feb. 2020, conference Name: Proceedings of the IEEE. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/8967260>
- [59]. L. Hobert, A. Festag, I. Llatser, L. Altomare, F. Visintainer, and A. Kovacs, "Enhancements of V2X communication in support of cooperative autonomous driving," *IEEE Communications Magazine*, vol. 53, no. 12, pp. 64–70, Dec. 2015, conference Name: IEEE Communications Magazine. [Online]. Available: <https://ieeexplore.ieee.org/abstract/document/7355568>
- [60]. O. Vermesan, R. John, P. Pye, G. Daalderop, K. Kriegel, G. Mitic, V. Lorentz, R. Bahr, H. E. Sand, S. Bockrath, and S. Waldhör, "Automotive Intelligence Embedded in Electric Connected Autonomous and Shared Vehicles Technology for Sustainable Green Mobility," *Frontiers in Future Transportation*, vol. 2, Aug. 2021, publisher: Frontiers. [Online]. Available: <https://www.frontiersin.org/journals/future-transportation/articles/10.3389/ffutr.2021.688482/full>
- [61]. Q. V. E. Hommes, "Review and Assessment of the ISO 26262 Draft Road Vehicle - Functional Safety," SAE International, Warrendale, PA, SAE Technical Paper 2012-01-0025, Apr. 2012, iSSN: 0148-7191, 2688-3627. [Online]. Available: <https://www.sae.org/publications/technical-papers/content/2012-01-0025/>

- [62]. C. Kreiner, R. Messnarz, A. Riel, D. Ekert, M. Langgner, D. Theisens, and M. Reiner, “Automotive Knowledge Alliance AQUA – Integrating Automotive SPICE, Six Sigma, and Functional Safety,” in *Systems, Software and Services Process Improvement*, F. McCaffery, R. V. O’Connor, and R. Messnarz, Eds. Berlin, Heidelberg: Springer, 2013, pp. 333–344.
- [63]. P. Kafka, “The Automotive Standard ISO 26262, the Innovative Driver for Enhanced Safety Assessment & Technology for Motor Cars,” *Procedia Engineering*, vol. 45, pp. 2–10, Jan. 2012. [Online]. Available: <https://www.sciencedirect.com/science/article/pii/S1877705812031244>
- [64]. C. Schmittner and Z. Ma, “Towards a Framework for Alignment Be-tween Automotive Safety and Security Standards,” in *Computer Safety, Reliability, and Security*, F. Koornneef and C. van Gulijk, Eds. Cham: Springer International Publishing, 2015, pp. 133–143.