Optimization of Wire-EDM Parameters To Calculate MRR and Measure Surface Finish On SS410

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Abstract - Wire Electro Discharge Machining (WEDM) process plays a significant role to cut complex and intricate shapes of components in all conductive materials. In order to improve the machining economics and the product accuracy of wed med parts a suitable modeling is essential. In this direction, several researchers have attempted previously. In this present analysis to predict the performance characteristics namely the Material Removal Rate (MRR) and surface roughness a general purpose statistical software, MINITAB was applied. Stainless Steel (ss410) material was selected as work material to conduct experiments. A 0.25 mm diameter Brass wire was applied as tool electrode to cut the material. Experiments were planned as per Taguchi's orthogonal array. Each experiment has been performed under different cutting conditions of pulse on time, off-time, wire speed, wire tension, dielectric pressure and current. In each experiment the performance characteristics such as material removal rate and surface roughness were carefully measured.

INDEX TERMS:- Material Removal rate, Surface roughness, Brass wire, WEDM, Taguchi's Orthogonal Array (OA).

CHAPTER 1

INTRODUCTION

The history of EDM Machining Techniques goes as far back as the 1770s when it was discovered by an English Scientist. However, Electrical Discharge Machining was not fully taken advantage of until 1943 when Russian scientists learned how the erosive effects of the technique could be controlled and used for machining purposes. When it was originally observed by Joseph Priestly in 1770, EDM Machining was very imprecise and riddled with failures. Commercially developed in the mid 1970s, wire EDM began to be a viable technique that helped shape the metal working industry we see today. In the mid-1980s. The EDM techniques were transferred to a machine tool. This migration made EDM more widely available and appealing over traditional machining processes.

The new concept of manufacturing uses non-conventional energy sources like sound, light, mechanical, chemical, electrical, electrons and ions. With the industrial and technological growth, development of harder and difficult to machine materials, which find wide application in aerospace, nuclear engineering and other industries owing to their high strength to weight ratio, hardness and heat resistance qualities has been witnessed. New developments in the field of material science have led to new engineering metallic materials, composite materials and high tech ceramics having good mechanical properties and thermal characteristics as well as sufficient electrical conductivity so that they can readily be machined by spark erosion. Non-traditional machining has grown out of the need to machine these exotic materials. The machining processes are non-traditional in the sense that they do not employ traditional tools for metal removal and instead they directly use other forms of energy. The problems of high complexity in shape, size and higher demand for product accuracy and surface finish can be solved through non-traditional methods. Currently, non-traditional processes possess virtually unlimited capabilities except for volumetric material removal rates, for which great advances have been made in the past few years to increase the material removal rates. As removal rate increases, the cost effectiveness of operations also increase, stimulating ever greater uses of nontraditional process. The Electrical Discharge Machining process is employed widely for making tools, dies and other precision parts.

EDM has been replacing drilling, milling, grinding and other traditional machining operations and is now a well established machining option in many manufacturing industries throughout the world. And is capable of machining geometrically complex or hard material components, that are precise and difficult-to-machine such

as heat treated tool steels, composites, super alloys, ceramics, carbides, heat resistant steels etc. being widely used in die and mold making industries, aerospace, aeronautics and nuclear industries. Electric Discharge Machining has also made its presence felt in the new fields such as sports, medical and surgical instruments, optical, including automotive R&D areas.

1.1 INTRODUCTION TO WIRE EDM:

In recent years, the technology of Wire Electrical Discharge Machining (WEDM) has been improved significantly to meet the requirements in various manufacturing fields, especially in the precision die industry. WEDM is a thermo electrical process in which material is eroded from the work piece by a series of discrete sparks between the work piece and the wire electrode (tool) separated by a thin film of dielectric fluid (demonized water) that is continuously fed to the machining zone to flush away the eroded particles. A small diameter wire ranges from 0.05 to 0.3mm is applied as tool electrode. The wire is continuously supplied from the supply spool through the work piece, which is clamped on the table by the wire traction rollers. A gap of 0.025–0.05mm is maintained constantly between the wire and work piece. A collection tank, which is located at the bottom, is utilized to collect the used wire. The schematic diagram of WEDM is shown in Fig.1



Fig 1.1. Detail of WEDM cutting gap

1.2 PROCESS PARAMETERS:

Significant machining parameters affecting the performance measures are identified as pulse off time, peak current, pulse on time, flow rate and wire tension. The effect of each control factor on the performance

measure is studied individually using the plots of signal to noise(S/N) ratio. The study demonstrates that the WEDM process parameters can be adjusted so as to achieve better metal removal rate, surface finish, wear ratio and dimensional deviation.

1.3 TAGUCHI'S PRINCIPLE:

Taguchi methods are statistical methods developed by Genichi Taguchi to improve the quality of manufactured goods, and more recently also applied to engineering, biotechnology, marketing and advertising. Taguchi employs design experiments using specially constructed table, known as "Orthogonal Arrays (OA)" to treat the design process, such that the quality is build into the product during the product design stage. Orthogonal Arrays (OA) are a special set of Latin squares, constructed by Taguchi to lay out the product design experiments. By using this table, an orthogonal array of standard procedure can be used for a number of experimental situations. The results obtained from the orthogonal array are then analyzed to achieve the following objectives:

- To estimate the contribution of individual quality influencing factors in the product design stage.
- To gain the best, or optimum, condition for a process, or a product, so that good quality characteristics can be sustained.
- To approximate the response of the product design parameters under the optimum conditions.

1.3.1 APPLICATION OF ORTHOGONAL ARRAY

Taguchi's Orthogonal Array (OA) analysis is used to produce the best parameters for the optimum design process, with the least number of experiments. The OA manages to transform a quality concept into the product design. The OA method is able to treat quality influencing factors at discrete levels, and often this method save time, and indirectly reduces the cost of hardware testing.

Thus, the OA is usually applied in the design of engineering products, test and quality development, and process development. All applications involved have a common objective that is to use Taguchi's OA method to build the quality into a product at the initial design stage.

CHAPTER 2

EXPERIMENTAL DETAILS

2.1 WORK PIECE MATERIAL:

In metallurgy, **stainlesssteel**, also known as **inoxsteel** or **inox** from French *inoxydable* (inoxidizable), is a steel alloy with a minimum of 10.5% chromium content by mass. Stainless steel is notable for its corrosion resistance, and it is widely used for food handling and cutlery among many other applications. Stainless steel is used for corrosion-resistant tools such as this nutcracker. Stainless steel does not readily corrode, rust or stain with water as ordinary steel does. However, it is not fully stain-proof in low-oxygen, high-salinity, or poor air-circulation environments. There are various grades and surface finishes of stainless steel to suit the environment the alloy must endure. Stainless steel is used where both the properties of steel and corrosion resistance are required.

Stainless steel differs from carbon steel by the amount of chromium present. Unprotected carbon steel rusts readily when exposed to air and moisture. This iron oxide film (the rust) is active and accelerates corrosion by making it easier for more iron oxide to form. Since iron oxide has lower density than steel, the film expands and tends to flake and fall away. In comparison, stainless steels contain sufficient chromium to undergo passivation, forming an inert film of chromium oxide on the surface. This layer prevents further corrosion by blocking oxygen diffusion to the steel surface and stops corrosion from spreading into the bulk of the metal. Passivation occurs only if the proportion of chromium is high enough and oxygen is present.

2.1.1 CHEMICAL COMPOSITION

The following table shows the chemical composition of Stainless steel 410.

| ELEMENT | CONTENT (%) |
|------------|-------------|
| Carbon | 0.15max |
| Chromium | 011.5-13.5 |
| Iron | Balance |
| Manganese | 11max |
| Phosphorus | 0.04max |
| Silicon | 1 max |
| Sulphur | 0.03max |

Table2.1 Chemical properties

2.1.2 PHYSICAL PROPERTIES

The following table shows the physical properties of Stainless steel 410.

| PROPERTIES | METRIC |
|------------------------|------------------------|
| Density | 7750 Kg/m ³ |
| Melting Point | 1460°C |
| Specific Gravity | 7.7 |
| Electrical Resistivity | 57 Ω·cm |

Table 2.2 Physical properties

2.1.3 MECHANICAL PROPERTIES

The following table shows the mechanical properties of Stainless steel 410.

| PROPERTIES | METRIC |
|---------------------------|--------------------------|
| Ultimate Tensile Strength | 75000 PSI |
| Poisson ratio | 0.24 |
| Elastic modulus | 29 X 10 ⁶ PSI |

Table 2.3 Mechanical properties

2.2 HEAT TREATMENT

The safe scaling temperature for continuous service is 1200°F (649°C). Carpenter Stainless Type 410, in both the annealed and heat-treated conditions, provides good corrosion resistance to mild atmospheres.



Fig 2.1 Stainless steel 410

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2.3 MACHINE SPECIFICATIONS:

The Stainless steel 410 was the target material used in this investigation. Experiments were performed using an Electronic wire cut electric discharge machine. The machine used for machining was YCM 500. A small diameter wire ranges from 0.05 to 0.3 mm is applied as tool electrode A gap of 0.025 to 0.05 mm is maintained constantly between the wire and work-piece. A collection tank which is located at the bottom is utilized to collect the wire after machining was performed. several researchers have attempted intelligent modelling and optimization techniques to improve the performance characteristics of WEDM.



Fig 2.2 Experimental Setup.

2.3.1 MACHINE TOOL

The specifications of the Machine tool are as follows,

The element zinc is added to copper to produce brass EDM wire, which is the most common EDM wire in use today. Brass wires for EDM are typically an alloy between 63/37 (American and European) to 65/35 (Asian), Cu/Zn ratio. Zinc has a lower melting/vaporization point which make it a better electrode material than copper, so the more zinc in the surface of an EDM wire, the faster it will cut. However, manufacturing difficulties arise when the volume of zinc approaches 40% and its crystalline structure changes to a gamma phase, causing the wire to become very brittle and difficult to draw. However, there are two wires being produced with 60/40 Cu/Zn content for faster cutting speeds.

| Design | Fixed column, moving table |
|----------------------------|-------------------------------------|
| | 700 700 |
| Table size | 500 x 500 mm |
| | 200 |
| Max. work piece height | 200 mm |
| Max work piece weight | 500 kg |
| Max. work piece weight | 500 Kg |
| Main table traverse (X Y) | 300 x 400 mm |
| | 300 X 100 mm |
| Aux. table traverse (u, v) | 80 x 80 mm |
| | |
| Max. taper angle | 0± 30° /50 mm |
| | |
| Max. JOG speed | 900 mm/min. |
| | |
| Resolution | 0.0005 mm |
| | |
| Max. wire spool capacity | 5 kg (up to DIN 160 / P5 |
| | |
| Wire electrode diameter | 0.25 mm (std.) 0.15, 0.20 mm (opt.) |

Table 2.4 Machine Specification

2.3.2 DIELECTRIC UNIT

The specifications of the Dielectric unit are as follows,

| Dielectric fluid | De ionized water |
|------------------|------------------|
| Tank capacity | 50 Liters |
| Filtration | Mineral bed |
| Cooling system | 1700 k Cal. |

Table 2.5 Dielectric unit specification.

2.3.3 PULSE GENERATOR

| Pulse generator type | ELPULS-40 A DLX |
|----------------------------------|----------------------------|
| CNC Controller | EMT 100W-5 |
| Controlled axes | X,Y,u,v simultaneous |
| Interpolation | Linear & Circular |
| Least input increment | 0.001 mm |
| Least command input (X,Y,u,v) | 0.0005 mm |
| Max. Programmable dim. (X,Y,u,v) | ± 99999.999 mm |
| Input power supply | 3 phase, AC, 415 V , 50 Hz |
| Connected load | 10 kVA |
| Average power consumption | 6 to 7 kVA |

Table 2.6 Pulse generator specification.

2.4 WIRE EDM CONDITION

The Wire-EDM conditions are as follows.

| WORK CONDITION | DESCRIPTION |
|------------------|-------------------------------------|
| Wire | Brass (diameter of 0.25mm) |
| Stainless steel | Rectangular shape (100mm*100mm*6mm) |
| Pulse ON(T ON) | 7-13 µs |
| Pulse OFF(T OFF) | 12-14 μs |
| Wire Tension | 10 N |
| Dielectric fluid | De-ionized water |

Table 2.7 Wire cut EDM Conditions.

2.5 MACHINE COMPONENTS:

2.5.1 TOOL:

The work piece and the wire represent positive and negative terminals in a DC electrical circuit, and are always separated by controlled gap, constantly maintained by the machine.

As the machine advances the wire through the work piece, it cuts a slot slightly larger than the wire diameter

The ideal wire electrode material for this process has three important criteria:

- ➢ high electrical conductivity
- ➢ sufficient mechanical strength
- > optimum spark and flush characteristics.



Fig 2.3 Wire EDM Tool

Mechanical strength, typically stated as tensile strength in PSI, needs to be sufficient to maintain wire straightness, with minimal vibration.

The ability of the wire material to enhance spark formation and the flushing process has become increasingly important with the growing need for both higher productivity and accuracy

2.5.2 COPPER WITH BRASS COATING:

Copper was the original material first used in wire EDM. Although its conductivity rating is excellent, its low tensile strength, high melting point and low vapor pressure rating severely limited its potential. Brass EDM wire is a combination of copper and brass typically alloyed in the range of 63–65% Cu and 35–37% br.

The addition of brass provides significantly higher tensile strength, a lower melting point and higher vapor pressure rating, which more than offsets the relative losses in conductivity. Brass quickly became the most widely used electrode material for general purpose wire EDM. It is now commercially available in a wide range of tensile strengths and hardness. Since brass wires cannot be efficiently fabricated with any higher concentration of zinc, the logical next step was the development of coated wires sometimes called plated or "stratified" wire. They typically have a core of brass or copper, for conductivity and tensile strength and are electroplated with a coating of pure or diffused zinc for enhanced spark formation and flush characteristics.

Originally called "speed wire" due to their ability to cut at significantly higher metal removal rates, coated wires are now available in a wide variety of core materials, coating materials, coating depths and tensile stress.

2.5.3 WIRE PATH:

When wire EDM was first introduced, copper wire was used on the machines because it conducted electricity the best. But as speeds increased, its limitations were soon discovered. The low tensile strength of copper wire made it subject to wire breaks when too much tension was applied. A good portion of the heat from the EDM spark was transferred to the wire and carried away from the work zone instead of using that heat to melt and vaporize the work piece. There is a vast array of wires to choose from with brass wire normally being used however, molybdenum, graphitized, and thick and thin layered composite wires are available for different applications. Needs for various wires include: optimizing for maximum cutting speeds, cutting large tapers, (soft brass) or cutting thick work.



Fig 2.4 Wire Movement

Wire diameters range from .004" through .014" with .010" being the most commonly used. The wire originates from a supply spool, then passes through a tension device (different diameter wires require different amounts of tension to keep it straight) It then comes in contact with power feed contacts where the electric current is applied. The wire then passes through a set of precision, round diamond guides, and is then transported into a waste bin. The wire can only be used once, due to it being eroded from the EDM process.(The used brass wire is sold to the scrap dealer for recycling.

2.6 IMPLEMENTATION OF TAGUCHI METHOD ON WIRE ELECTRICAL DISCHARGE MACHINING (WEDM)

In this study the relationship between control factors & responses like Material Removal Rate, Surface finish and Dimensional deviations are established. The Taguchi method is used to formulate the experimental layout, to analyze the effect of each parameter on the machining characteristics, and to predict the optimal choice for input. Various important input combinations as formulated by Taguchi, is worked out in a wire electric discharge machine. Calculated results and lab results are tabulated as shown below, so that the best output's can be found.

2.6.1 L₁₆ ORTHOGONAL ARRAY (8 Parameters and two levels)

The Taguchi orthogonal array of four levels is shown in the tabular column. Taguchi methods are statistical methods developed by Genichi Taguchi to improve the quality of manufactured goods, and more recently also applied to engineering, biotechnology, marketing and advertising.

Taguchi employs design experiments using specially constructed table, known as "Orthogonal Arrays (OA)" or otherwise known as Fractionalized Factorial Method.

The number of degrees of freedom was calculated from the number of parameters identified and their number of levels of variation.

In the Taguchi method, most all of the observed values are calculated based on 'the higher the better' and 'the smaller the better'. Thus in this study, the observed values of MRR, Ra and Cs were set to maximum, intermediate and minimum respectively.

In this study, Taguchi method, a powerful tool for parameter design of performance characteristics was used to determine optimal machining parameters for minimum surface roughness and maximum MRR in WEDM. By this, the process parameters which influence the products are separated into two main groups: control factors and noise factors. Four important machining parameters were used as control factors and each parameter was designed for four levels and orthogonal array was chosen for the experiments and the results are presented in below Table.

| EXP. No | C 1 | C 2 | C 3 | C 4 | C 5 | C 6 | C 7 | C 8 |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 2 | 1 | 1 | 1 | 2 | 1 | 2 | 2 | 2 |
| 3 | 1 | 1 | 2 | 1 | 2 | 1 | 2 | 2 |
| 4 | 1 | 1 | 2 | 2 | 2 | 2 | 1 | 1 |
| 5 | 1 | 2 | 1 | 1 | 2 | 2 | 1 | 2 |
| 6 | 1 | 2 | 1 | 2 | 2 | 1 | 2 | 1 |
| 7 | 1 | 2 | 2 | 1 | 1 | 2 | 2 | 1 |
| 8 | 1 | 2 | 2 | 2 | 1 | 1 | 1 | 2 |
| 9 | 2 | 1 | 1 | 1 | 2 | 2 | 2 | 1 |
| 10 | 2 | 1 | 1 | 2 | 2 | 1 | 1 | 2 |
| 11 | 2 | 1 | 2 | 1 | 1 | 2 | 1 | 2 |
| 12 | 2 | 1 | 2 | 2 | 1 | 1 | 2 | 1 |
| 13 | 2 | 2 | 1 | 1 | 1 | 1 | 2 | 2 |
| 14 | 2 | 2 | 1 | 2 | 1 | 2 | 1 | 1 |
| 15 | 2 | 2 | 2 | 1 | 2 | 1 | 1 | 1 |
| 16 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 |

2.6.2 SURFACE ROUGHNESS TESTER

The Surface roughness of Specimen is checked by Surface roughness tester. Its Specification are given below

| Measuring range | 17.5mm |
|---------------------|------------------|
| Measuring Speed | 0.25mm/s |
| Detector range | -200μm to 160 μm |
| Measuring force | 4mN |
| Stylus tip radius | 5 μm |
| Data Storage | Memory Card |
| Conical Taper angle | 90° |
| Drive Unit | Standard type |
| Power Supply | Ni-MH battery |

Table 2.9 Surface roughness tester Specification

2.7 DESIGN OF EXPERIMENTS:

Design of experiments is a powerful analysis tool for modeling and analyzing the influence of process variables over some specific variable, which is an unknown function of these process variables. The most important stages in the design of experiment lie in the selection of the control factors. Combining the experiment design theory and the quality loss function concept proposed by Taguchi in the 1960s is widely used to solve and improve industrial product quality and reliability.

The experimental layout for the machining parameters using the orthogonal array was used in this study. This array consists of four control parameters and four levels. An orthogonal array gives a more reliable estimate of

the factor effects with fewer tests compared to traditional methods. The process parameters along with their values at four levels are given in Table.

2.7.1 INPUT PARAMETERS:

| S.No | OV | TOFF | T _{ON} | SV | WT | WA | F | WF |
|------|----|------|-----------------|----|----|----|-----|----|
| 1 | 12 | 11 | 14 | 40 | 8 | 4 | 4.5 | 2 |
| 2 | 12 | 11 | 12 | 40 | 12 | 2 | 10 | 2 |
| 3 | 12 | 3 | 14 | 45 | 8 | 2 | 10 | 2 |
| 4 | 12 | 3 | 12 | 45 | 12 | 4 | 4.5 | 2 |
| 5 | 8 | 11 | 14 | 45 | 12 | 4 | 10 | 2 |
| 6 | 8 | 11 | 12 | 45 | 8 | 2 | 4.5 | 2 |
| 7 | 8 | 3 | 14 | 40 | 12 | 2 | 4.5 | 2 |
| 8 | 8 | 3 | 12 | 40 | 8 | 4 | 10 | 2 |
| 9 | 8 | 3 | 12 | 45 | 12 | 2 | 10 | 4 |
| 10 | 8 | 3 | 14 | 45 | 8 | 4 | 4.5 | 4 |
| 11 | 8 | 11 | 12 | 40 | 12 | 4 | 4.5 | 4 |
| 12 | 8 | 11 | 14 | 40 | 8 | 2 | 10 | 4 |
| 13 | 12 | 3 | 12 | 40 | 8 | 4 | 4.5 | 4 |
| 14 | 12 | 3 | 14 | 40 | 12 | 4 | 10 | 4 |
| 15 | 12 | 11 | 12 | 45 | 8 | 4 | 10 | 4 |
| 16 | 12 | 11 | 14 | 45 | 12 | 2 | 4.5 | 4 |

Table 2.10 Input parameters



Fig 2.5 Clamping of Work Piece

2.8 FORMULAE USED:

Changes in the electrode weight, material weight and elapsed time were recorded after each machining test. The MRR was evaluated for each cutting condition by measuring the average amount of material removed and the required cutting time.

Material Removal Rate (MRR) = KTVmm³/min

Where K=Kerf, k=0.25+2(0.05) =0.35mm

T=thickness=12.43mm

Kerf k=D+2G

D=dia of wire=0.25mm

G=wire-work gap(or spark gap) =0.05mm

CHAPTER 3

RESULTS AND DISCUSSIONS

| S.No | OV | TOFF | T _{ON} | SV | WT | WA | F | WF | MRR | Ra |
|------|-----|------|-----------------|-----|-----|----|---------|-------|----------------------|-------|
| | (V) | (µs) | (µs) | (V) | (N) | | mm²/min | m/min | mm ³ /min | (µm) |
| 1 | 12 | 11 | 14 | 40 | 8 | 4 | 4.5 | 2 | 5.747167 | 2.81 |
| 2 | 12 | 11 | 12 | 40 | 12 | 2 | 10 | 2 | 7.868002 | 2.92 |
| 3 | 12 | 3 | 14 | 45 | 8 | 2 | 10 | 2 | 5.838011 | 2.691 |
| 4 | 12 | 3 | 12 | 45 | 12 | 4 | 4.5 | 2 | 6.013657 | 2.619 |
| 5 | 8 | 11 | 14 | 45 | 12 | 4 | 10 | 2 | 7.836008 | 2.412 |
| 6 | 8 | 11 | 12 | 45 | 8 | 2 | 4.5 | 2 | 8.849749 | 2.828 |
| 7 | 8 | 3 | 14 | 40 | 12 | 2 | 4.5 | 2 | 5.098674 | 2.47 |
| 8 | 8 | 3 | 12 | 40 | 8 | 4 | 10 | 2 | 4.984026 | 2.686 |
| 9 | 8 | 3 | 12 | 45 | 12 | 2 | 10 | 4 | 5.880663 | 2.257 |
| 10 | 8 | 3 | 14 | 45 | 8 | 4 | 4.5 | 4 | 5.76375 | 2.544 |
| 11 | 8 | 11 | 12 | 40 | 12 | 4 | 4.5 | 4 | 7.816191 | 2.63 |
| 12 | 8 | 11 | 14 | 40 | 8 | 2 | 10 | 4 | 6.819885 | 2.969 |
| 13 | 12 | 3 | 12 | 40 | 8 | 4 | 4.5 | 4 | 5.828248 | 3.091 |
| 14 | 12 | 3 | 14 | 40 | 12 | 4 | 10 | 4 | 5.943935 | 2.571 |
| 15 | 12 | 11 | 12 | 45 | 8 | 4 | 10 | 4 | 8.509975 | 2.374 |
| 16 | 12 | 11 | 14 | 45 | 12 | 2 | 4.5 | 4 | 8.644712 | 2.752 |

Table 3.1 Results of Orthogonal Array for L₁₆ Taguchi Design

3.1 ANALYSIS AND DISCUSSION OF EXPERIMENTAL RESULTS

The response table was used to establish statistically significant machining parameters and the influence of these parameters on the surface roughness and the MRR. In Taguchi method, a loss function is used to

calculate the deviation between the experimental value and the desired value. This loss function is further transformed in to a signal-to-noise (S/N) ratio. There are several S/N ratios available depending on the type of characteristics; lower the better (LB), nominal is the best (NB), and higher is better (HB). In WEDM, the lower surface roughness and higher MRR are indication of better performance. For the HB and LB, the definitions of the loss function (L) for machining performance results (MRR, surface roughness) of n repeated number are,

$$L_{HB} = 1/n \sum_{i=1}^{n} 1/Y_{MRR}^2$$
(2)

$$L_{LB} = 1/n \sum_{i=1}^{n} Y_{SF}^{2}$$
(3)

Where Y_{MRR} and Y_{SF} are the response for material removal rate and surface finish respectively and n denotes the number of experiments. The S/N ratio can be calculated as a logarithmic transformation of the loss function as shown below:

S/N ratio for MRR = -10 log 10 (
$$L_{HB}$$
) (4)

S/N ratio for SF = -10 log 10 (
$$L_{LB}$$
) (5)

Regardless of the category of the performance characteristics, greater S/N values correspond to a better performance. Therefore, the optimum level of the machining parameters is the level with the greatest S/N ratio value. By applying these Equations from (2) to (5), the S/N ratio values for each experiment of L16 (Table 4) was calculated (Table Based on the analysis of S/N ratio, the optimal machining performance for the MRR from means graph was obtained.

The optimum machining performance for the surface finish was obtained at 120μ sec. pulse-on time , 54 μ sec. pulse- off time , 7 wire tension and 70% Cutting speed. Based on the above results the optimal cutting conditions obtained for surface finish are A2B3C2D1.

| LEVEL | OV | ON | OFF | SV | WT | WA | F | WF |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 16.32 | 16.30 | 16.73 | 16.52 | 16.13 | 16.53 | 16.58 | 16.57 |
| 2 | 17.14 | 17.16 | 16.73 | 16.95 | 17.33 | 16.94 | 16.88 | 16.90 |
| Delta | 0.82 | 0.86 | 0.00 | 0.43 | 1.20 | 0.41 | 0.30 | 0.33 |
| Rank | 3 | 2 | 8 | 4 | 1 | 5 | 7 | 6 |

Table 3.2 Response Table for Signal to Noise Ratios for MRR

| LEVEL | OV | ON | OFF | SV | WT | WA | F | WF |
|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| | | | | | | | | |
| 1 | -8.544 | -8.534 | -8.51 | -8.232 | -8.822 | -8.757 | -8.223 | -8.307 |
| | | | | | | | | |
| 2 | -8.417 | -8.427 | -8.444 | -8.730 | -8.140 | -8.205 | -8.733 | -8.655 |
| | | | | | | | | |
| Delta | 0.127 | 0.107 | 0.074 | 0.498 | 0.681 | 0.553 | 0.515 | 0.348 |
| | | | | | | | | |
| Rank | 6 | 7 | 8 | 4 | 1 | 2 | 3 | 5 |
| | | | | | | | | |

Table 3.3 Response Table for Signal to Noise Ratios for Ra



Fig 3.1 Taguchi analysis on MRR.



Fig 3.2 Taguchi analysis on Ra

From the response table we can infer that wire tension influence the parameters to the most critical level in MRR. Following that order pulse ON time and OFF time influences them in the next level. So the optimized order of the parameters in the calculation of MRR is A2B2C2D2E2F2G2H2. The optimized values are,

| PARAMETERS | OV | ON | OFF | SV | WT | WA | F | WF |
|------------------|----|----|-----|----|----|----|---|----|
| OPTIMIZED | 8 | 11 | 12 | 45 | 12 | 2 | 5 | 4 |
| VALUES | | | | | | | | |

Table 3.4 Optimized Values for MRR

Also from the response table of surface roughness, wore tension influences the most and then comes the water flow and pulse ON and OFF time parameters. The ordered and the optimized values for the surface roughness is A1B1C1D2E1F1G2H2.

| PARAMETERS | OV | ON | OFF | SV | WT | WA | F | WF |
|---------------------|----|----|-----|----|----|----|---|----|
| OPTIMIZED VALUES | 12 | 7 | 14 | 45 | 8 | 4 | 5 | 4 |





Fig.3.3 Normal probability plot, randomness, experimental run and histogram for residual plots for means of Ra.



Fig.3.4 Normal probability plot, randomness, experimental run and histogram for residual plots for means of MRR.

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CHAPTER 4

CONCLUSION

4.1. CONCLUSION

This paper has presented an investigation on the optimization and the effect of machining parameters on the MRR and the surface finish in WEDM operations. The effect of various machining parameter such as pulse on time, pulse off time, wire tension, and Cutting speed has been studied through the machining of SS410 steel. The level of importance of the machining parameters on the MRR and the surface finish was determined by using Response table Method, the highly effective parameters on both the MRR and the surface finish were found, as pulse on time, wire tension and delay time more than the other parameters. An optimum parameter combination for the maximum MRR and minimum surface roughness was obtained by using the analysis. The confirmation tests indicated that it is possible to increase MRR and decrease surface roughness significantly by using the proposed statistical technique. The experimental results confirmed the validity of the used Taguchi method for enhancing the machining performance and optimizing the machining parameters in WEDM operations.

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