An Overview of Various Approaches for Static and Dynamic Surveillance Systems

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Abstract— Video surveillance has lengthy been in use to display protection-sensitive regions which include banks, branch stores, highways, crowded public locations, and borders. The develop in computing electricity, availability of great ability garage gadgets and excessive speed network infrastructure paved the way for less expensive, multi-sensor video surveillance systems. Traditionally, the video outputs are processed on-line by using human operators and are stored to tapes for later use handiest after a forensic event. The growth in the variety of cameras in conventional surveillance structures overloaded each the human operators and the garage devices with excessive volumes of facts and made it infeasible to make certain proper tracking of sensitive areas for lengthy instances. To filter redundant statistics generated using an array of cameras, and boom the reaction time to forensic occasions, helping the human operators with the identity of important events in the video using the use of "clever" video surveillance systems has come to be an essential requirement. The making of video surveillance structures "smart" requires fast, dependable and strong algorithms for moving item detection, type, monitoring and pastime analysis.

Keywords— video surveillance, object tracking, mean square error

I. INTRODUCTION

Video surveillance systems have lengthy been in use to monitor security sensitive areas. The history of video surveillance includes three generations of structures which might be called 1GSS, 2GSS, and 3GSS [1].

The first technology monitoring systems (1GSS, 1960-1980) were based totally on analog subsystems for picture acquisition, transmission, and processing. They extended human eye in spatial feel with the aid of transmitting the outputs of several cameras monitoring a set of websites to the displays in a first control room[2]. They had the important drawbacks like requiring excessive bandwidth, hard archiving and retrieval of activities due to the large variety of video tape necessities and challenging online event detection which only trusted human operators with limited attention span..

The making of video surveillance structures "smart" requires fast, reliable and robust algorithms for shifting object detection, type, monitoring and interest evaluation. Starting from the 2GSS, many studies has been dedicated to the development of these clever algorithms[3].

Moving item detection is the primary step for also analysis of the video. It handles segmentation of moving gadgets from desk-bound heritage gadgets. It now not handiest creates a focal point of attention for better stage processing but additionally decreases computation time appreciably. Commonly used strategies for item detection are historical past subtraction, statistical fashions, temporal differencing and optical waft. Due to dynamic environmental conditions which include illumination changes, shadows and waving tree branches inside the wind item segmentation is a difficult and substantial problem that needs to be handled well for a robust visual surveillance device[4].

Video surveillance is essentially the most energetic study matter in machine vision for people and vehicles. Right here the intention is to enhance an intelligent visual surveillance method through re-inserting the age ancient classical method of monitoring via human operators. The inducement in doing is to design a video surveillance approach for movement detection and object monitoring.

II. LITERATURE SURVEY

The use of item detection, tracking and class algorithms are not limited to video surveillance best. Other software domains also benefit from the advances within the studies on these algorithms. Some examples are the digital truth, video compression, human machine interface, augmented truth, video enhancing and multimedia databases. Table.1 gives a tabular representation of various contributions made in this research direction.

Author	Year	Contribution
Brice,Fenema, Pavlidis Rosenfeld and Kak	1970	Worked on constrained optimization problem of controlling the smoothness of boundaries in an image representing each object significantly[1].
Otsu	1979	Proposed a histogram based technique to maximize the class variance among different

		alaggag angh rangesenting a	Liu		proposed heatrons a
		classes, each representing a single object[2].	Liu		proposed background subtraction to notice
		single object[2].			relocating areas in an
Mumford Shah	1985,	worked on localized image			imagegraph via taking the
Mulliora Shan	1989	segmentation problem and			change between present
	1707	concluded to region			and reference background
		growing based image			imagegraph in a pixel-by
		segmentation approach,			means of-pixel[5].
		which is the most standard	Collins		Developed a hybrid process
		one yet. Threshold			that combines three-frame
		selection in image			differencing with an
		segmentation is a			adaptive background
		problematic task. It			subtraction mannequin for
		provides vital information			their VSAM (Video
		about image and play			Surveillance and
		important role in			Monitoring) assignment[6].
		segmentation of image.	Desa & Salih		Proposed a blend of
		Several different methods			background subtraction and
		for choosing a threshold			frame change that elevated
		exist; users can manually			the previous outcome of
		choose a threshold value,			background subtraction and
		or a thresholding algorithm			body change[6].
		can compute a value	Sugandi		Pproposed a new system
		automatically, which is			for object detection using
		known as automatic			body change on low
		threshold [4]. One of such			decision image[7].
		simpler methods used is to	Julio Cezar		Proposed a background
		select either the mean or			model, and comprise a
		median value, depending on the condition whether			novel procedure for
		the object pixels are			shadow detection in grey
		brighter than the	0 + 1		scale video sequences[8].
		background.	Satoh		Proposed a brand new
Rudolph E.		Kalman filter operates on			manner for object
Kalman,"		input data to perform a			monitoring employing block matching algorithm
Tunnun,		statistically			established on PISC
		optimal solution of the			image[5].
		used system, its output gets	Sugandi		Proposed monitoring
		filtered of any noisy	Sugandi		technique of moving folks
		component rendered either			making use of digital
		due to input noise or output			camera peripheral
		noise. In today's era this			increment sign correlation
		technique is used in			image[9].
		multitude of navigation	Beymer &	1999	Proposed in stereo digital
		systems such as missile etc.	konolige		camera situated object
		It is being too used in the	C		tracking, use kalman filter
		systems of VR (Virtual			for predicting the objects
		Reality) and AR			position and speed in x-2
		(Augmented Reality) [3] to			dimension[3].
		track the human motions in	Liu	2001	Proposed background
T • 4		a virtual space.			subtraction to detect
Lipton		Proposed frame change that			moving regions in an
		use of the pixel-sensible			image by taking the change
		variations between two			between current and
		frame portraits to extract			reference background
Stouffor 9		the moving areas[4].			image by a pixel-via-pixel.
Stauffer & Grimson		proposed a Gaussian blend model situated on			It's extremely sensitive to
GIIIISUII		background mannequin to			change in dynamic scenes
		realize the thing[2].			derived from lighting
		realize the thing[2].			fixtures and extraneous

		routine and many others[10].			Via monitoring every small blob, the moving human is
Stauffer & Grimson,	1997	Proposed a Gaussian blend mannequin centered on background mannequin to realize the item[10].	McKenna	2000	successfully tracked. Proposed an adaptive background subtraction system where colour and
Lipton	1998	Proposed frame difference that use of the pixel-clever variations between two body images to extract the moving areas. This process may be very adaptive to dynamic environments, but normally does a terrible job of extracting all of the central pixels, e.g., there could also be holes left inside of relocating entities. So as to overcome disadvantage of two-frames differencing, in some cases three-frames differencing is used[9].			gradient understanding are combined to manage with shadows and unreliable colour cues in motion segmentation. Monitoring is then performed at three stages of abstraction: areas, individuals, and agencies. Every neighborhood has a bounding box and regions can merge and break up. A human is composed of a number of areas grouped together below the values of geometric structure constraints on the human physique, and a human
Collins 2000	2000	Developed a hybrid procedure that mixes three- frame differencing with an	Cheng & Chen	2006	workforce consists of a number of men and women grouped together[6]. Proposed a colour and a
	adaptive background subtraction model for his or her VSAM (Video Surveillance and Monitoring) challenge. The hybrid algorithm successfully segments moving regions in video without the defects of temporal differencing and			spatial function of the article to identify the track object. The spatial function is extracted from the bounding box of the article. In the meantime, the color points extracted is imply and regular value of every object[7].	
Desa & Salih	2004	background subtraction[12]. Proposed a combo of background subtraction and frame difference that accelerated the earlier results of background subtraction and body	Czyz	2007	Proposed the colour distribution of the item as commentary model. The similarity of the objects measurement utilizing Bhattacharya distance. The low Bhattacharya distance corresponds to the high
Wren et al 19	1997	difference[13]. Explored using small blob facets to track a single human in an indoor	Sugandi	2007	similarity[9]. Object monitoring employing block matching algorithm centered on PISC image[2].
		environment. In their work, a human physique is regarded as a mixture of some blobs respectively representing various body	Satoh	2001	Proposed object identification employing color and spatial information of the tracked object[7].
		ingredients comparable to head, torso and the 4 limbs. The pixels belonging to the human physique are assigned to the different physique phase's blobs[8].	Cheng & Chen	2006	Proposed implementation of an current algorithm for tracking the article by using utilizing Block matching process is done. An computerized video

	- 1		
	1	surveillance is used by	Stauffer and Proposed ,advise a
		personal firms,	Grimson probabilistic process using
		governments and public	a combination of Gaussian
		corporations to fight in	for picking out the
		opposition to terrorism and	background and foreground
		crime, public protection in	objects. The entire
		airports, bus stand, railway	approach of monitoring the
		station, town facilities and	moving object is illustrated
		hospitals. It has also to find	in [6]. The block matching
		applications in site visitors	approach is well described
		surveillance for effective	in [7], which got utilized
		management of transport	generally.
		networks and street	Satoh 2001 Considers the brightness
		safeguard. Video	change in all of the pixels
		surveillance system	of the blocks relative to the
		comprise mission akin to	considered pixel. Literature
		movement detection,	suggests the block in PISC
		tracking, and endeavor	image with block
	1	attention. Out of the project	dimension is 55 pixels.
		acknowledged above,	Thus, one block contains
		detection of moving object	25 pixels. The blocks of th
		is the first predominant	PISC image in the prior
		step and positive	frame are outlined. In a
		segmentation of moving	similar fashion, the blocks
		foreground object from the	of the PISC image in the
		background ensures object	current body are defined.
		classification, personal	To check the matching
		identification, tracking, and	criteria of the blocks in two
		undertaking analysis,	successive frames, analysis
		making this later step more	is finished using correlatio
		efficient[13].	value that expresses. This
Hu		Labeled motion detection	equation calculates the
		into three main lessons of	correlation price between
		procedure as body	block within the previous
		differencing, background	body and the current one
		subtraction and Gaussian	for all pixels within the
		mixture[12].	block. The excessive
Nowak	2003	Showed how the	correlation value suggests
		parameters of a mixture of	that the blocks are matched
	1	Gaussians for which each	every other[9].
	1	and every node of a sensor	
		community had distinctive	
	1	mixing coefficients could	III. CONCLUSION
	1	be estimated utilising a	
		allotted version of the	In this research article, we have focused our investigatio
	1	famous expectation-	over the utility of various approach for video surveillance
		maximization (EM)	For this sake a tabular listing is mentioned in this work
	1	algorithm[10].	Major fields of research in surveillance system includ
EM. Kowalczyk	2004	Proposed a related gossip-	segmentation approach for various condition, parametric an
and Vlas-sis		founded allotted algorithm	non parametric approach for object tracking, featur
Kowalczyk and	1	called Newscast EM for	matching based surveillance model and spatial processing of
Vlassis		estimating the parameters	pixel information to improve the frame suspectibility for
. 100010	1	of a Gaussian mixture.	object detection. Over all we can say that this art may play
	1	Random pairs of nodes	vital role for basic understanding of various research sub
		repeatedly alternate their	dimensions in this field.
	1	parameter estimates and	
		combine them by way of	REFERENCES
	1	weighted averaging[7].	[1] J. N. Mann, W. Barry, "Surveillance: Inventing and Using Wearabl
		weighted averagnig[/].	Computing Devices", Surveillance & Society, vol. 1, no. 3, 2003.

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